

A LINEAR PROGRAMMING APPLICATION TO AIRCREW SCHEDULING



A thesis presented to the Faculty of the U.S. Army Command and General Staff College in partial fulfillment of the requirements for the degree

MASTER OF MILITARY ART AND SCIENCE

by

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> Fort Leavenworth, Kansas 1980



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This study demonstrates the feasibility of using linear programming and computer assisted techniques to improve the efficiency of allocating training sorties in a fighter squadron. The study also identifies shortfalls in TAC's existing computer systems and lack of necessary programs to measure aircrew proficiency. The conclusion of the study is that while the application of linear programming techniques may improve the overall efficiency of sortic allocation, it is not currently possible to implement such a system without further research and development of supporting systems. Therefore, it is recommended that additional research be devoted to refinning the techniques presented in this study for use as computer terminals become available within individual squadrons.

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Carlton L. Pannell, Maj, USAF U.S. Army Command and General Staff College Fort Leavenworth, Kansas 66027

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ABSTRACT

A LINEAR PROGRAMMING APPLICATION TO AIRCREW SCHEDULING, by Major Carlton L. Pannell, USAF, 141 pages.

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Chapter I

INTRODUCTION

Background

From the late 1960s until the termination of the Vietnam conflict, numerous deficiencies existed in training of Tactical Air Command (TAC) aircrews. Aircrews were sent into combat with little experience in their assigned aircraft and with little or no specialized mission training. (22:5) TAC recognized aircrew training programs required revision and in 1972 conducted a Tactical Fighter Symposium to study the problems and develop recommendations to improve the situation. (22:8)

In 1973, a conference was held at Headquarters United States Air Force to evaluate a new idea in aircrew training. (22:9) Out of this meeting came the Designed Operational Capability (DOC) concept. This concept directed individual units be assigned specific training missions or DOCs.

In July of the following year, the new training concept was implemented with the publishing of a multi-command 51- series manual. (22:9) The basic manual was divided into individual volumes covering each of the aircraft assigned to the Tactical Air Forces (TAF). The basic volume outlined the flying training program in terms of a multi-level approach to matching available resources and training requirements called a Graduated Combat Capability.

Again in 1976, the Air Force took action to verify the status of aircrew training programs in TAC. Air Force directed the Air Force Inspection System Command (AFISC) to perform a Functional Management Inspection (FMI) to identify aircrew training problems and "zero-in" on areas adversely impacting on the quality of aircrew training. The team visited the Air Staff, five major command (MAJCOM) headquarters, and twenty-four air bases within the TAF. The inspection methods used were questionnaires and in-depth interviews with commanders, staffs, and aircrews. (6:1)

Several complex, interrelated problems concerning aircrew training were surfaced by AFISC. Although these problems had been getting worse for years, the true effects were masked due to the highly qualified aircrews. (6:1) The lower experience levels found in fighter units today, coupled with economic and personnel constraints, have highlighted the need to correct existing deficiencies before too much damage occurred to the overall level of combat readiness. The basic finding of the FMI was that flying units needed tailored training programs optimized to programmed wartime tasks and unique unit situations. (6:2)

Today, Air Force military end strength is at its lowest point since 1950. (15:135) Between 1973 and 1979, the Air Force accounted for over sixty percent of the total Department of Defense (DoD) active military reductions. In addition, over the last ten years Air Force manpower declined by thirty-seven percent while military costs increased by thirty percent. (15:136 and 143) Since 1968, our total force -- Air National Guard (ANG), Air Force Reserve (AFRES), and Active duty -- aircraft inventory has dropped from over 15,000 aircraft to a'most

9,000 aircraft (a reduction of forty-one percent). During this same period, the total number of flying hours was reduced by fifty-eight percent, yet the operating costs increased by seventy-five percent. (15:144)

The TAF is faced with many constraints to providing optimum training to today's fighter force. Fewer resources, budgetary limitations, and lower aircrew experience levels are the main restrictions. As flying hours and training sorties are cut, it becomes imperative to efficiently allocate the available sorties to ensure adequate readiness of the fighting force.

Readiness is a concept that integrates the diverse factors that affect the ability to deploy, engage, and sustain effective combat forces. It starts with the overall availability and proficiency of U.S. fighting men. (18:1)

TAF's aircrew training is a readiness issue which has considerable impact on this nation's combat capability. To satisfy the need for a strong tactical air arm, the TAF developed basic aircrew training programs designed to be tailored to the needs and capabilities of the individual aircrews. My experience has been that too many of the units assigned to TAC try to meet the standards of training manuals, rather than attempt to really tailor the flying training program to the individual's abilities.

Problem Statement

The basic problem then is to develop a system or program which will allow the individual squadron scheduler to allocate available training sorties in a way which will not only meet training guidance but also satisfy the training needs of individual aircrews based on their proficiency. Training sorties are allocated to pilots so they

can attain or maintain proficiency. The allocation process is meant to provide proficient crews and a combat ready squadron. (10:10) The state of combat readiness of the squadron depends on the proficiency of individual pilots. To ensure that each pilot can maximize his proficiency within the constraints of available resources, each pilot must be allocated sufficient sorties to maintain the desired proficiency level. To be effective any system or program must be simple and easy to use. It must be flexible and responsive to the needs of the scheduler since the guidelines and resources which are availabe to the scheduler change frequently. While there may be many suitable programs or systems which would meet these goals (linear programming, dynamic programming, goal programming, etc.), only one approach will be studied due to the limited time available for research.* Due to the simplicity of a linear programming approach and the availability of software to solve very large linear programming models, this research will focus on the possible use of linear programming as an aircrew scheduling aid.

Objective

The objective of this study is to determine if linear programming can be employed to improve scheduling effectiveness by distributing sorties based on the priorities assigned by the scheduler. Although this study is limited to units possessing the A-7D aircraft, the application of linear programming techniques should be equally valid for units with other tactical weapons systems. To be able to

^{*}A brief discussion of linear programming, dynamic programming, and goal programming can be found in Appendix B.

apply to linear programming techniques, one must be familiar with flying training regulations and scheduling problems.

Flying Training

Multi-command manual 51-50, <u>Tactical Fighter/Reconnaissance</u>

<u>Aircrew Training</u>, establishes the flying training program for TAF

aircrews referred to as the Graduated Combat Capability (GCC). (12:1-1)

The GCC concept is a three level approach which attempts to match

resources and training requirements. The levels are defined as:

- 1. Level A. This is the basic mission ready standard, as determined by the MAJCOM, and reflects the minimum level to which a crew must be trained to perform the unit's primary mission.
- 2. Level B. Additional training required to increase proficiency, lower crew/aircraft attrition, and increase the capability to accomplish the unit's full tasking.
- 3. Level C. This level represents the complete training program for the unit based on full employment tasking. (12:1-2)

Associated with the three levels of training are three progressive phases which an aircrew transitions. The three phases are defined as:

- 1. Initial Qualification Training (IQT). The training to initially qualify an aircrew in basic flying duties regardless of the unit's operational mission.
- 2. Mission Qualification Training (MQT). That training in addition to IQT needed to progress the aircrew to designated mission status.
- 3. Continuation Training (CT). The training for a qualified aircrew member to maintain mission status... (12:1-2)

Another categorization which must be understood is mission status. Aircrews are either mission ready (MR) or mission support (MS). An MR aircrew is one who can be sent into combat and accomplish

the unit's primary mission without additional training. An MS aircrew is one who maintains basic qualifications, but would not enter combat without additional training to reach MR status. (12:1-3)

Both MR and MS aircrews are further classified by experience level. Aircrews are designated as either experienced or inexperienced based on the number of hours flown and the type of aircraft in which the hours were accumulated. An experienced aircrew must meet the following criteria:

- 1. 1000 or more total hours flying time and 300 hours minimum in the unit aircraft, or
 - 2. At least 500 hours in the unit aircraft, or
- 3. 100 hours in the unit aircraft and previously categorized as experienced in a specified tactical aircraft. (12:1-3)

 Those aircrews who do not meet the above requirements are designated inexperienced.

The sortie program outlined in multi-command manual 51-50 is built around a minimum and standard sortie basis. The standard sortie program sets forth the optimum requirements which must be flown to maintain an assigned training level. The minimum sortie program establishes the least number of sorties which must be flown to maintain an assigned training status. These two programs are further divided into specific sortie types and events which must be accomplished during each six month training cycle.

The minimum sortie and event requirements for all aircrews flying fighter aircraft are listed in Table 1. (12:1-4) This training should be scheduled to ensure a regular sortie flow is accomplished by individual aircrews. (10:34) A regular or steady flow of training is

needed to keep aircrews from losing proficiency or currency in an event or type of mission. Sorties which must be used to regain currency reduce the number of training opportunities which can be used to complete GCC tasking.

Table 1
Semiannual Requirements

Crew Position	Instrument Penetrations	Precision Instrument Approaches	Nonprecision Approaches	Night Landings	Night Sorties	Minimum Total Sorties	Air Refueling MR/MS
Pilot	6	12	12	2	2	30	3/2

With the minimum sortie requirements established, the next consideration is the standard sortie program which establishes the specific guidance for developing unit training programs. Since this study concentrates on an $\underline{A-7D}$ unit, Table 2 presents an illustrative active duty $\underline{A-7D}$ training program extracted from TAC Manual 51-50, Vol III. (13:3-3)

Table 2
Active Duty A-7D Training Program

	Lev	el A	Level	B Lev	el C
	Day	Night		Day	Night
Sorties					
WD/SATa b	22/18	6	11/6	1	9/5
Maverick	6		4/2 (8/6)	(2)	
WD/SAT ^a Maverick ^b SAR ^d ACBT	6		4/2	(2) 2	
Subtotal GCC	34/30	6	19/10	14/10	
Total GCC	40/36	•	59/46	73/56	
.Total	50/46		71/57	86/68	

Note: See Appendix A for an explanation of the sortie types.

- a. Weapons Delivery/Surface Attack Tactics
- b. Sorties employing captive or live Maverick air-to-ground missiles
- c. Search and Rescue
- d. Air Combat Training

The numbers under the columns labeled Level A, Level B, and Level C in Table 2 are broken out according to the requirements for inexperienced/experienced aircrews respectively. Level A shows the minimum sorties needed to maintain an MR status. Level B lists the added sorties recommended by TAC when a unit can provide more sorties than required to maintain Level A. Level C includes the remaining sorties to meet TAC's overall training goal. While the subtotal and total GCC tasking is self-explanatory, the difference between total GCC and total sorties is not readily apparent. This difference results from the addition of collateral sorties to the GCC requirements to cover unprogrammable requirements.

Collateral sorties are additional sorties which are used for planning purposes to allow for training directed by Air Force requirements (checkrides, deployments, etc.), upgrade sorties, recurrency

sorties, and non-effective GCC training sorties. For computational purposes, collateral sorties are determined by taking ten percent of the total GCC sorties and adding six more sorties. (12:4-4) Table 3 illustrates the computation of total planning sorties.

Table 3
Collateral Sortie Computation

Total GCC Sorties	+ Collateral Sorties	= Total Planning Sorties
15-24	8	23-32
25-34	9	34-43
35-44	10	45-54
45-54	11	56 -6 5
55-64	12	67-76
65-74	13	78-97
75-84	14	89-98
85-94	15	100-109

Flying the total number and type of sorties listed in Table 2 is insufficient in itself to maintain a given aircrew status. Aircrews must also meet the GCC event training program requirements. The event training program sets a qualification or proficiency level and a minimum number of event repetitions which must be attained. Of the events required, the weapons delivery qualification is the most important.

To establish and maintain a weapons delivery qualification, an aircrew must meet the standards for each type of delivery which his level of training dictates. Each type of delivery event has scoring criteria which determines if a given delivery is a hit (qualifying) or a miss (not qualifying). To qualify in a delivery event, a minimum number of hits must be achieved. Additionally, fifty percent of conventional ordnance deliveries and forty percent of Maverick deliveries must be hits. Table 4 shows the minimum required hits per type

delivery event (bombing, strafe, and Maverick) based on the type of range used for scoring the delivery. (12:5-5)

Table 4
A-7D Required Hits

Type Event/Delivery		Hits
Conventional Ordnance Conventional Range Tactical Range		6/4 3/5
	TOTAL	9/9
Strafe Conventional Range Tactical Range		6/4
	TOTAL	6/4
Maverick		6
·	TOTAL	6

Note: Hits are listed in order for inexperienced/experienced pilots.

To illustrate qualification requirements, an example using an experienced aircrew on a conventional range, dropping conventional ordnance will be presented. If the experienced aircrew were to drop four qualifying bombs consecutively, he would be qualified, since he achieved the minimum number of qualifying deliveries by Table 4. However, if the same aircrew were to have four consecutive misses, he would then have to drop at least four more bombs, all hits, to reach fifty percent hits and therefore be qualified.

Requirements of the GCC event training program vary just as the sortic program depending on the level of training assigned.

The specific requirements based on Levels A, B, and C are listed in Table 5. There are additional constraints not apparent from looking at the table. First, night events listed in Table 5 are only required

A-7D GCC Event Training Program (13:3-5) Table 5

Event	Level A Day Ni	l A Night	Level B	Level Day	Level C Day Night
Computed Low Angle Strafe Computed Low Angle Bomb Computed Low Angle Low Drag	Qual Qual Qual	Fam			2 2 Qual
Computed Dive Bomb Computed High Altitude Dive Bomb High Angle Strafe Flare Deliverv	Qual	Fam 1(Ont)	Fam Fam	Qua] Qua]	Qual Fam Fam
Air Support Radar Team Delivery Low Level Visual Mavigation Night/Tactical/Radar Navigation	9	2	2.5	~ e	. 2
Surface Attack Tactics with FAC Surface Attack Tactics Alert Maverick Full Scale Weapons Delivery	2	1(Opt)	2 2 Qual	- 2	7
Composite Force Training Radar Deliveries (Day or Night) Electronic Warfare Range Training Search and Rescue Helicopter Escort	12	-	2 2 2		2 - 2

Notes.

- Qual means qualification is required.
 Fam means that the aircrew is to be familiar with the event but qualification in the event is not required.
 Opt means the event is optional.

if the unit is tasked to maintain a night capability. Second, deliveries performed during WD sorties and/or SAT sorties, either day or night, may be counted for WD qualifications. Lastly, at least two deliveries in each weapons event must be performed in a manual mode.

Scheduling

Squadron schedulers face a difficult job. (24:40) They must attempt to maximize crew proficiency, morale, and safety while ensuring available resources are neither over nor under used. Schedulers must function in a very fluid environment where availability and priorities of individual aircrews, training areas, suitable weather conditions, and aircraft compound the problem of achieving training objectives. When the scheduler looks at aircrew availability he must consider several factors including the number of aircrews involved, their experience level, priorities of individuals, and the frequency of personnel turnovers.

The aircrews assigned to a squadron are based on the number of aircraft the unit is authorized. Air Force Pamphlet 173-13, <u>USAF Cost and Planning Factors</u>, sets the ratio of aircrews to aircraft. For an A-7D unit the aircrew/aircraft ratio is 1.25 to 1.0. Table 6 shows the relationship for two normal sized squadrons. (8:156 and 159)

Table 6
Aircrew/Aircraft Planning Factors

Type of	Aircraft	Manning	Authorized	Sta	ff
Aircraft	<u>Authorized</u>	Ratio	<u> Aircrews</u>	Active	ANG
A-7D	24	1.25	30	7	13
A-7D	18	1.25	23	-	13

Based on an active duty A-7D unit with twenty-four aircraft and a 1.25 manning ratio, the scheduler would be working with thirty primary aircrews and seven staff aircrews. Assuming a forty percent experienced ratio for aircrews, the squadron would be made up of twelve experienced primary aircrews and eighteen inexperienced primary aircrews.* The seven staff aircrews would normally meet the requirements for designation as experienced aircrews.

Although the number and experience level of assigned aircrews is a basic consideration, it is still necessary to determine or establish the priority which each aircrew should be given when allocating available sorties. The GCC program provides priority to inexperienced aircrews over experienced aircrews but leaves any other guidelines to be established by the unit commander. This aspect becomes critical when there are insufficient sorties for each member of the unit to meet the training standards and some of the aircrews need extra training to achieve required standards.

Today, personnel policies provide for stabilized three year tours at most bases. To the scheduler this means the unit will lose, on the average, one-third of its members each year. For planning purposes, this turnover equates to five new aircrews per six month training cycle.

The unit training program must efficiently transition new aircrews from IQT through MQT and into CT in as brief a period as

^{*}In Volume III of the Rated Distribution and Training Management Executive Committee Minutes (published semiannually) the aircrew experience ratio is addressed by base and weapons system. While the ratio varies from unit to unit, the ratio for TAC, as a whole, is close to 40/60.

possible. To accomplish this task, the scheduler must be familiar with the requirements and time constraints associated with each phase of training (IQT, MQT, and CT).

The IQT program consists of ten base sorties; however, more sorties may be flown if needed. The first eight sorties are prerequisites for the initial qualification/instrument check on the ninth sortie. The tenth sortie is a night transition sortie which may be accomplished in conjunction with the night sortie in the MQT phase. All ten sorties must be flown with an IP and completed in less than two months. (13:1-1 - 1-4)

Upon completion of IQT aircrews may enter MQT or CT depending on the final status (MR/MS) to be achieved. Aircrews expected to maintain an MS status do not have to complete MQT. The number of sorties to be flown during MQT is determined by the unit commander based on the upgrading aircrew's experience, the assigned GCC level, and ensuring training continuity. The MQT phase must be completed within a two month time frame. (12:3-1 - 3-3)

To enter CT aircrews must have completed IQT and MQT or equivalent training. Since specific CT requirements were discussed in the previous section, the requirements will not be repeated here. It is important to note that it may take at most four months to complete both IQT and MQT which would leave two months of CT to be accomplished.

The CT requirements can be prorated based on the following formula:

Months available 6 Events/sorties/hours = Prorated Requirement required per six month

Fractions of .5 or greater will be rounded to the next larger number. Those fractions less than .5 will be dropped. (12:1-5) An individual who has only two months left in the training cycle would have to complete one-third of the CT requirements.

In addition to normal training sorties, aircrews must take an annual instrument and qualification checkride. These checkrides must be accomplished with a Standardization/Evaluation Flight Examiner (SEFE). This requirement results in a need for thirty-seven or more sorties per training cycle. Additional sortie requirements result from the various upgrade programs (flight lead, instructor pilot, etc.).

The next major area facing the scheduler is the availability of training areas. There are very limited numbers of low level training routes, weapons ranges, and airspace for air-to-air work which individual units can use on a daily basis. Most of these training areas must be shared with other units which limits the number and type of sorties which can be flown each day by any one unit. Additionally, weather may preclude use of an area even if it was available to the unit.

Weather is an important factor in developing any flying schedule. TAC Manual 25-5, <u>Programmed Flying Training Factors</u>, provides the scheduler with charts on the expected days suitable for flying at specific bases. (11:A5-1 - A5-5) The local weather officer is also important as a source for historical data on both seasonal and daily weather conditions. Knowledge of the weather is critical because it determines not only if flying is possible, but when flying can be accomplished, what areas can be used, and what type of mission can be flown.

The type and number of available sorties is also dependent on the maintenance capabilities of the unit. With a squadron of twenty-four aircraft, fifteen aircraft would normally be flyable to meet the daily flying schedule. Normal use rates would provide about twenty-two sorties per day.*

In addition to the factors which limit the amount of training which can be accomplished, the scheduler must be aware of the need to maintain accurate records of completed training so that requirements can be forecast. Tracking of training accomplishments and currency is a considerable task. Recognizing the benefits to be gained by employment of an automated system to perform these tasks, the MAJCOMs developed and implemented their own computerized management systems.

Automated Flying Training Management Systems

Today, the Military Airlift Command (MAC) has its Automated Resources Management System (MACARMS), the Strategic Air Command (SAC) has its Automated Resources Management System (SACARMS), and TAC has its Automated Flying Training Management System (TAFTRAMS). Actions are underway to combine all of these individual systems into one Air Force wide Operations Resources Management System (AFORMS) in the 1982 time period. Since this study deals with TAC requirements and systems, only TAFTRAMS will be discussed in this section.

^{*}Computation of available aircraft and sortie generation capability is developed in Chapter II on pages 24 and 55.

TAFTRAMS was developed to:

... record and track continuation training activities required by applicable MAJCOM 51-series manuals for use by unit level managers and to support the flow of summarized data to higher headquarters agencies. (14:1-1)

To attain this goal, TAFTRAMS was designated as the official record of CT accomplishments and each unit in TAC was directed to use the system to monitor training directed by MAJCOM 51-series manuals.

TAFTRAMS is a computerized management system developed, tested, and modified by TAC. It is currently a batch processing system run by the local Data Processing Installation (DPI) on Burroughs model 3500/3700/4700 computers. (14:2-4) While the capability to run the system on a daily basis exists, units normally request updates only three times a week. The time span from delivery of the card deck to the data processing center to receiving the computer print-outs is normally overnight.

Computer input data is created from pre-punched or manually punched standard eighty character cards. During a regular cycle up to 5,000 cards can be input. A greater number of cards can be input only with special coordination with the DPI.

Processing time in the Central Processing Unit varies with the

... number of other programs running concurrently in the computer, the number of aircrews, and the amount of data stored for each (i.e., the later in the training cycle, the longer the run time). (14:2-8)

Access to and time on the computer is somewhat determined by the other base agencies which also use the system. Considerable justification is required for any increased use or cost associated with the DPI.

Chapter II

RESEARCH DESIGN AND PROCEDURES

Introduction

The objective of this thesis is to determine if linear programming can be used as a management tool to improve scheduling effectiveness by allocating sorties based on priorities assigned by the squadron scheduler. To determine if linear programming can be used as a scheduling aid, a linear programming model will be developed and used in conjunction with a computer program to generate a squadron sortie allocation for one training cycle. The constraints of the linear model will be modified to evaluate the effects on the sortie allocating process.

This chapter is divided into four subsections. In the first section an imaginary squadron is constructed for use in the linear programming model. Individual pilots are identified with alphanumeric characters and their specific qualifications and characteristics are delineated. In the next section an explanation of the system used to designate the variables in the mathematical model is provided. In the third section the scheduling constraints are developed. The final section illustrates a representative sample of the mathematical relationships which exist based on the considerations of the first three sections.

The Squadron Composition

To formulate the linear program, a basic <u>A-7D</u> unit will be established with current manning factors. This squadron will be based on an active duty squadron with twenty-four aircraft. Manning for the squadron will be based on guidelines found in Air Force Pamphlet 173-13, <u>USAF Cost and Planning Factors</u>, which are summarized in Table 6, page 12. The squadron will consist of thirty primary pilots. Twelve of the thirty pilots would be experienced and the remaining eighteen would be inexperienced. Of the twelve experienced pilots, three will be designated as instructor pilots (IPs). In addition to the thirty primary pilots, there will be seven staff pilots. All seven of the staff pilots will be considered experienced. Three of the staff will be IPs (one of the IPs will be a SEFE) and the remaining four will be MS pilots. Table 7, page 21, provides a summary of the applicable pilot categorizations.

Since each pilot is unique and possesses distinct abilities, it is possible to develop programs to rank the pilots according to their proficiency in comparison with other unit pilots. Some objective programs already exist to rank pilots (such as TOP GUN competition) and some programs will have to be developed.* Where objective measurement systems do not currently exist, subjective rankings could be used with

^{*}TOP GUN competition is a common practice in TAC fighter squadrons. While there are many variations, the pilots are ranked in each weapons delivery event according to their number of hits and/or average miss distance from the target.

only a marginal degradation in results.* To develop rankings for this imaginary squadron a monte carlo simulation approach was used.** A randomly generated number was assigned to each pilot and the resultant distribution was then employed to artificially order the pilots from top to bottom. An unweighted ranking from each type sortie was used to determine an overall position within the squadron. These rankings are depicted in Table 8, page 22.

Definitions of Variables

The variables for this problem represent the number of each type sortie flown by each unit pilot under its current GCC tasking. Each of the thirty-seven pilots assigned to the squadron may fly seven different types of sorties resulting in a total of 259 variables. The general notation for the variables is XPPSS, where PP is the pilot number and SS is the sortie type.*** The alphanumeric designators for the variables are listed for each pilot in Appendix C.

^{*}If each of the squadron IPs subjectively rank all of the pilots in each type of sortie and a composite ranking is developed from these separate lists, the relative pilot rankings are not likely to significantly differ from a ranking developed through a very systematic approach.

^{**}For a discussion of monte carlo simulation the reader should consult Modern Elementary Statistics by John E. Freund or An Introduction to Quantitative Methods for Decision Making by Richard E. Trueman.

^{***}The numeric designators for the various sorties are: 01 (WD), 02 (SAT), 03 (MAV), 04 (ACBT), 05 (SAR), 06 (NIGHT), and 07 (COLS).

Table 7
Pilot Categorization

Pilot Designator	Primary Aircrew MR MS	Staff MR MS	Experience Level Exper/Inexper		Instructor Pilot
			X		
P2	Χ			X	
Р3	X		Χ		
P4	Χ			X	
P5	Χ		X		X
P6	Χ		Χ		
P7	Χ		X		
P8 ·		X	X		
P9	Χ		Х		Х
P10	Χ			X	
Pll	Χ			X	
P12	Χ			Χ	
P13		Χ	X		X
P14	Χ		X		
P15	X			X	
P16		X٠	Χ	• •	χ
P17	Χ		••	X	.,
P18	X		Χ	,,	
P19	X			X	
P20	X			X	
P21	^	X	Х	^	
P22	X	^	~	X	
P23	x		X	^	X
P24	x		^	X	^
P25	x			x	
P26	x			â	
P27	^	χ	X	^	
P28	X	^	^	X	
P29	x			x	
P30	x		X	Λ	
P31	â		X		
P32	X		^	χ	
P33	X		X	۸	
P34	X		^	χ	
P34 P35	X		•	۸	
	۸	v	X X		v
P36	v	X	λ	v	X
P37	X			X	

Table 8
Pilot Ranking

		Type Sortie					0vera11
Group*	Ranking	WD	SAT	MAV	ACBT	SAR	Position
	1	P14	P23	P36	P10	P26	P23
I	2	P16 P9	P9 P18	P13 P9	P18	P3	P9 P5
-	2 3 4	P32	P18	P14	P1.3 P5	P16 P23	P14
	5	Pll	P31	P18	P37	P37	P7
	6	P7	P7	P17	P30	P33	P18
II	7 · 8	P5 P23	P5 P14	P29 P32	P19 P26	P21 P35	P16 P33
11	9	P31	P33	P23	P6	P28	P3
	10	P19	P2	P24	P9	P34	P29
	11	P2	P29	P35	P23	P36	P31
	12	P27	P27	P20	P12	P7	P13
III	13 14	P35 P17	P28 P4	P7 P4	P3 P32	P2 P5	P6 P36
	15	P20	P13	P6	P29	P11	P26
	16	P3	P36	P27	P31	P15	P32
	17	P24	Р3	P33	P4	P22	P37
	18	P15	P20	P15	P15	P6	P11
	19	P25	P6 P22	P5 P1	P33 P16	P20 P30	P4 P2
	20 21	P29 P26	P22 P16	P37	P16	P30 P24	P20
	22	P6	P30	P28	P22	P12	P35
	23	P34	P25	P12	P36	P31	P15
	24	P33	P10	P30	P1	P19	P19
	25	P4	P17	P26	P25	P32	P28
	26 	P10	P34	P16	P24	P14	P25
	27 28	P12 P18	P21 P35	P19 P31	P14 P34	P17 P29	P17 P30
IA	20 29	P28	P12	P3	P20	P9	P24
	30	P8	P26	P25	P7	P13	P12
	31	P1	P37	P21	P]]	P18	P10
	32	P13	P15	P8	P28	P4	P34
	33	P36	P8	P11	P8	P25	P22
	34 35	P37 P30	P1 P32	P10 P22	P35 P27	P8 P10	P27 P21
٧	35 36	P30 P22	P32 P24	P22 P34	P27	P10 P27	P2 (
	37	P21	P19	P2	P21	Pl	P8

^{*}Use of this column is addressed on page 26.

Constraints

The constraints which the scheduler faces fall into four categories: (1) the number of sorties which can be supported by the available aircraft, (2) the number of each type of sortie which can be supported with other resources, (3) training requirements from applicable guidance, and (4) the training required due to individual pilot proficiency.* These constraints will be covered in order and the mathematical relationships will be developed using the variables listed in Appendix C.

The first consideration is the total number of sorties available from the twenty-four assigned aircraft. TAC Manual 25-5, Programmed Flying Training Factors, provides the basic standards used for computations involved in determining sortie availability.** Two factors are needed, the number of flying days available and the number of sorties which can be flown per day. Figure 1 shows the computation of available flying days for planning purposes. This data is combined with the data in Figure 2 which shows the computation of the number of sorties available per day to determine the total sorties available. When the data from these two figures are combined it can be determined that 2,024 sorties would be available in the

^{*}The variability of weather conditions and availability of the areas from one location to another will not be specifically covered but are usually taken into account when determining the total number and type of sorties available for planning.

^{**}The computation of available flying training days is covered in Attachment 5 and the computation of aircraft utilization and generation rates is covered in Attachment 10 of the manual.

first training cycle (January - June) and 2,464 during the second training cycle (July - December) for a total of 4,488 for the year.

Number of Days Available (January - June)	181
Less:	
Weekends 52	
Holidays 3	
Weather Days <u>34</u>	
· —	89
Number of Flying Days Available First Training Cycle	92
Number of Days Available (July - December)	184
Less:	
Weekends 43	
Holidays 6	
Holidays 6 Weather Days <u>23</u>	
·	72
Number of Flying Days Available Second Training Cycle	112
Number of Flying Days Available Both Training Cycles	204

Figure 1
Available Flying Days

22.15

Number of Aircraft Assigned 24 Less: $24\%^{\text{C}} = 5.76$ $5\%^{\text{C}} = 1.20$ NORM Gb NORS G 6.96 Flyable Aircraft 17.04 Flyable Aircraft Less: Non Mission Capable Aircraft $2\%^{C} = .34$ Mission Capable Aircraft Mission Capable Aircraft Less: Load Crew Training QC Inspections 1.07 Available Flyable Aircraft per Day 15.63 Gross Sorties per Day = (Sortie Rate)(Available Aircraft) (1.446)(15.63) =22.6 Less: Non Delivered Aircraft $2\%^{C} = .45$.45

Figure 2

Available Sorties per Day

a. Aircraft grounded for maintenance.

Net Sorties Available per Day for Planning

b. Aircraft grounded for supply.c. These factors are based on programmed maintenance data and should be verified with a unit's historical records.

d. QC Aircraft/Day = $\frac{\text{(Possessed Aircraft/Mo)(OC Rate)}}{\text{Duty Days/Mo}} = \frac{(24)(.10)}{21} = .114$

The next constraint is based on the total number of each sortie type which can be supported with available resources. The restriction could be due to the availability of training ordnance or training areas. This constraint does not apply to collateral sorties. Table 3, page 9, shows the relationship of collateral sorties to GCC sorties. From this relationship it can be determined that the minimum number of collateral sorties for planning would be 222 (six sorties per pilot). The maximum number of collateral sorties for planning would be 222 plus ten percent of the total number of GCC sorties flown.

The next step is to develop a list of constraints based on current training guidelines. By combining the requirements from applicable training directives, the commander's direction, and research of historical records, tables can be set up to identify both minimum and maximum sortic constraints. Table 9 shows the maximum sortic constraints and Table 10 shows the minimum sortic constraints for Level C. Each unit would need to develop similar tables based on their unique situations for each level of training.

Table 9

Maximum CT Sortie Requirements

Status	WD	SAT	MAV	ACBT	SAR	NIGHT	TOTAL
MR EXP	12	13	10	10	8	11	76
MR INEXP	14	20	12	12	10	15	97
MS	6	10	6	6	5	6	39

<u>Notes</u>.

1. MR staff flies at ninety percent of MR EXP level.

2. CT sorties for IQT/MQT pilots will be a prorated share of the Level A requirements.

Table 10
Minimum CT Sortie Requirements

Status	WD	SAT	MAV	ACBT	SAR	Night	Total
MR EXP	5	5	3	4 ·	6	4	64
MR INEXP	7	4	4	6	6	4	83
MS	2	2	2	2	2	2	30

Notes.

- 1. MR staff flies at ninety percent of MR EXP level.
- 2. CT sorties for IQT/MQT pilots will be a prorated share of the Level A requirements.

The final area of concern is the number of sorties each pilot needs to maintain a given level of proficiency based on his own abilities. To determine the relative proficiency of each pilot a standardized program should be employed to ensure uniform results. Once the pilots are ranked from top to bottom, it is possible to develop and use a simple modification of Table 8, page 22, to provide additional sorties to those pilots with lower proficiency levels. Table 11 is an example of a simple program to allocate additional sorties to the lower ranking pilots. The unit is divided into five groups. The highest group flies at the minimum sortie rate while the lower groups gain additional sorties. The determination of the number of sorties which each group should gain can be determined from historical data in the squadron. For this evaluation, each of the groups will be given one additional sortie.* From Table 10 an experienced MR pilot in

^{*}The selection of additional sorties given to each group should provide a stepped increase which will not result in the maximum sortie constraint being exceeded.

group I would get a minimum of five WD sorties and an inexperienced pilot in this same group would get seven WD sorties. In group II an experienced pilot would get six WD sorties (five sorties from Table 10 plus one sortie from Table 11) and an inexperienced pilot would get eight WD sorties (seven sorties from Table 10 plus one sortie from Table 11). This allocation process provides priority for inexperienced pilots.

Table 11
Minimum Sortie Adjustment Factors

Group	Sortie Rate
I	Minimum
II	Minimum + 1
III	Minimum + 2
IV	Minimum + 3
V	Minimum + 4

In addition to the maximum and minimum constraints, it is possible to simply set a specific level of sorties to be flown by letting the sortie type equal a fixed number (i.e., WD = 12). If the total of two sortie types is to remain constant an inverse relationship must be established (i.e., WD + SAT = 34). If desired, a given sortie type can be weighted relative to another type by stating the desired ratio (i.e., WD = 2SAT).

Linear Equations and Inequalities

In this section the foundation on which the linear programming model is based is developed. The objective statement, the constraints on the number of each type sortie, and constraints for a representative sample of pilots are developed.

The goal of the scheduler is to maximize the unit's combat readiness by optimizing the allocation of sorties so that no resources will be wasted. To meet this goal, the constraints developed for each pilot will provide a means by which sortie allocation can be efficiently accomplished. The objective function then becomes to minimize the use of resources. The objective function can be expressed as:

Minimize Z = X0101+X0102+X0103+ ... +X3705+X3706+X3707

The next area of concern is the development of constraints for each sortic type. This would normally be based on local conditions as discussed in the section on constraints. However, since this is not realistic with the imaginary squadron, the constraints were developed using Table 9, page 26, and Table 7, page 21. The results are summarized in Table 12.

From Table 12, the following constraints can be established for each type sortie:

- (1) X0101+X0201+X0301+ ... +X3501+X3601+X3701 < 462
- (2) X0102+X0202+X0302+ ... +X3502+X3602+X3702 < 551
- (3) X0103+X0203+X0303+ ... +X3503+X3603+X3703 ₹ 362
- (4) X0104+X0204+X0304+ ... +X3504+X3604+X3704 < 357
- (5) x0105+x0205+x0305+ ... +x3505+x3605+x3705 < 313
- (6) X0106+X0206+X0306+ ... +X3506+X3606+X3706 < 411
- (7) X0107+X0207+X0307+ ... +X3507+X3607+X3707 < 522

With the constraints established for the individual sortie types, the next consideration is to establish a series of constraints for a representative sample of the pilots typically found in a unit. To accomplish this task, examples will be provided using pilots P1, P2, P3, P16, and P17.

Table 12
Sortie Distribution

PILOT	WD	SAT	MAV	ACBT	SAR	NIGHT	COLS	TOTAL SORTIE
Pl	6	10	6	6	5	6	0	39
P2	14	20	12	12	10	15	14	97
P3	12	13	10	10	8	11	12	76 27
P4 P5	14	20	12 10	12 10	10	15 11	14 25	97 89
P6	12 12	13 13	10	10	8 8	11	12	76
P7	12	13	10	10	Q	11	12	76 76
P8	6	10	6	6	8 5	6	0	39
P9	12	13	10	10	8	11	25	89
P10	14	20	12	12	10	15	14	97
Pii	14	20	12	12	10	15	14	97
P12	14	20	12	12	10	15	14	97
P13	11	12	9	7	7	10	25	81
P14	12	13	10	10	8	11	12	76
P15	14	20	12	12	10	15	14	97
P16	11	12	9	7	7	10	25	81
P17	13	_ 7	5	6	8	14	18	61
P18	12	13	10	10	8	11	12.	76
P19	14	20	12	12	10	15	14	97
P20	14	20	12	12 7	10	15	14	97
P21 P22	11 13	12 7	9 5	6	8 8	10 4	9 18	65 61
P22 P23	12	13	10	10	8	11	25	89
P24	14	20	12	12	10	15	14	97
P25	14	20	12	12	10	15	14	97
P26	14	20	12	12	10	15	14	, 97
P27	6	10	6	6	5	6	Ö	39
P28	14	20	12	12	10	15	14	97
P29	14	20	12	12	10	15	14	97
P30	15	10	6	6	8	3	16	64
P31	12	13	10	10	8	11	12	76
P32	14	20	12	12	10	15	14	97
P33	12	13	10	10	8	11	12	76
P34	13	7	5	6	8	4	8	51
P35	16	12	7	7	8	3	9	62
P36	11	12	9	7	7	10	25	81 07
P37	14	20	12	12	10	15	14	97
TOTALS	462	551	362	357	313	411	522	2,978

Pilot Pl is an MS staff pilot. The constraints applicable to

```
Pl are:
```

```
X0101+X0102+X0103+X0104+X0105+X0106+X0107 < 39
(8)
(9)
      X0101+X0102+X0103+X0104+X0105+X0106+X0107 > 30
(10)
       X0101 < 6
(11)
       x0101 > 2.
(12)
       X0102 ≤ 10
       x0102 > 2
(13)
       X0103 ≤ 6
(14)
       0.03 \ge 2
0.04 \le 6
(15)
(16)
       \begin{array}{c} X0104 \ge 2 \\ X0105 \le 5 \end{array}
(17)
(18)
       X0105 > 2
(19)
(20)
       X0106 \le 6
(21)
       X0106 > 2
       X0107 < 9
(22)
(23)
       X0107<sub>.</sub> ≥ 0
```

Pilot P2 is an inexperienced MR pilot. The following constraints

apply:

```
(24)
      X0201+X0202+X0203+X0204+X0205+X0206+X0207 \le 97
(25)
      X0201+X0202+X0203+X0204+X0205+X0206+X0207 \ge 83
(26)
      X0201 < 14
      X0201 ≥ 8
X0202 ≤ 20
X0202 ≥ 15
(27)
(28)
(29)
      X0203 \le 12
(30)
(31)
      X0203 > 8
(32)
      X0204 < 12
(33)
      X0204 > 8
      X0205 ≤ 10
(34)
(35)
      X0205 > 8
(36)
      X0206 < 15
(37)
      X0206 > 6
(38)
      X0207 ₹ 14
(39)
      X0207 > 8
```

Pilot P3 is an experienced MR pilot. The following constraints

apply:

```
X0303 > 6
(47)
48)
      X0304 ₹ 10
(49)
      X0304 > 6
(50)
      X0305 ₹8
(51)
      X0305 > 4
52)
      X0306 ₹ 11
53)
      X0306 ≥ 6
      X0307 ₹ 12
54)
(55)
      X0307 ≥ 6
```

For an experienced MR IP line 40 would be modified to indicate \leq 89, line 41 would be changed to \leq 77, line 54 would become \leq 25, and line 55 would be \geq 19.

Pilot P16 is an MR staff IP. The constraints which apply are:

```
x1601+x1602+x1603+x1604+x1605+x1606+x1607 \le 81
(57)
      x1601+x1602+x1603+x1604+x1605+x1606+x1607 > 56
      X1601 ≤ 11
(58)
      X1601 ≥ 6
59)
      X1602 < 12
(60)
      X1602 > 7
(61)
      X1603 <u>₹</u>9
(62)
      X1603 \ge 5
(63)
      X1604 <u>< </u>7
(64)
      X1604 > 4
(65)
      X1605 < 7
(66)
      X1605 \ge 5
(67)
      X1606 ₹ 10
(68)
      X1606 > 5
(69)
      X1607 ≤ 25
(70)
      X1607 \ge 19
(71)
```

The last example is pilot P17 who represents a new unit pilot who has completed IQT and MQT in four months and is required to accomplish a prorated share (one-third) of Level A CT sorties. The appropriate constraints are:

```
X1701+X1702+X1703+X1704+X1705+X1706+X1707 \le 61
(72)
(73)
      X1701+X1702+X1703+X1704+X1705+X1706+X1707 \ge 49
(74)
      X1701 \le 13
(75)
      X1701 > 10
(76)
      X1702 ≤ 7
(77)
      X1702 \ge 4
(78)
      X1703 ≤ 5
      X1703 ≥ 3
X1704 ≤ 6
(79)
(80)
(81)
      X1704 ≥ 6
```

With a mathematical model developed for the imaginary squadron, the data can be translated into a format to be processed by a computer using an existing program to solve linear programming models. The computer solution represents a feasible semiannual sortic allocation.*

The flexibility and utility of this scheduling technique will be evaluated in the next chapter.

^{*}The computer solution derived for this model was obtained using a Control Data Corporation (CDC) model 6500 computer and the CDC APEX III program.

Chapter III

PROGRAM AND SOLUTION

This chapter is divided into two sections. The first section pertains to the computer program created for this particular research. The second section relates to the solution generated for the mathematical model developed for the imaginary $\underline{A-7D}$ squadron used as the data base for the problem.

Computer Program

In Chapter II a data base was established and used to develop an LP model. The next step was to write a computer program to simplify transforming the data base into an input for a computer program capable of solving LP problems. The program written for this purpose is listed in Appendix D.

Prior to explaining how the program works it will be necessary to explain some of the terminology used and the arrays or matrixes employed to hold data for processing. To familiarize the reader with the terminology the following definitions are offered:

Terminology	Meaning
P1	A matrix used to hold the input category for each pilot.
P2	A matrix used to hold ranking data for each pilot for each type sortie.
P3	A matrix used to hold total and sortie type maximums and minimums for each pilot (a row from Dimension Table.

RNKRNK

A matrix for holding the pilot's ranking in rank order for each sortie type. For example, if pilot X is ranked first in sortie type J then RNKRNK (1,J)=X.

CUTPER

An array which holds the percentages used to establish the group a pilot would fall into (see Table 8, page 22). Current values are .10, .30, .70, and .90.

CUTPT

An array which holds the numerical cut point determined from the total number of pilots entered and the percentages set in CUTPER.

DIMENSION TABLE

A matrix which holds values for each pilot category entry (currently 21). The values are maximums and minimums for TOTAL, WD, SAT, MAV, ACBT, SAR, NIGHT, and COLS. The columns with negative values reflect variable quantities set by the pilot's ranking in an event. The minus sign is a device used in the computer program to determine if the entry has a fixed or variable value and should not be construed to mean the actual value is negative.

FIXED SET

A value determined by the sign of column in DIMENSION TABLE. The value is TRUE if the sign is positive and FALSE if the sign is negative.

MAXFLT

An array which holds maximum allowed total sorties by sortie type.

RESPNS

An array used to hold input data moved to Pl and P2.

RESPNS(1)

Pilot number.

RESPNS(2)

Training category.

RESPNS(3)

Post training category.

RESPNS(4)

Months to complete training.

RESPNS(5)

Training status after training.

RESPNS(6)

Pilot status.

RESPNS(7)

IP status.

RESPNS(8)

Experience level.

RESPNS(9)

GCC level.

RESPNS(10)

Pilot rank (1).

TOTPLT

Total number of pilots.

MAXPLT Maximum number of pilots for the program (currently

50).

PNMBR Pilot number.

TNGCAT Training category

POSTCT Post training category (MR or MS).

CATGRY Category (Primary or Staff).

EXPER Experience level.

STATUS Pilot mission status (MR or MS).

ENTRY Row of DIMENSION TABLE.

POINT Column to be entered in the DIMENSION TABLE.

BASE Absolute value of entry in POINT.

BUMP Amount by which BASE is to be increased.

RERANK A subroutine used to rerank pilots based on the

limitation that each pilot must be allocated at least as many sorties as the next pilot ranked lower in order. Pilots who would violate this

constraint are removed from ranking.

RANK A matrix used to hold initial pilot ranking by type

sortie.

RANK(2) A matrix used to hold pilots after reranking.

MAX A matrix which holds modified rows of the DIMENSION

TABLE.

MAXP A column in MAX matrix which contains the maximum

sortie constraints.

MINP A column in MAX matrix which contains the minimum

sortie constraints.

CARDS A subroutine used to generate an output format

suitable for input into the CDC APEX III program.

CHRANK A subroutine used to check the ranks input to ensure

they do not exceed number of total pilots or repeat.

The computer program used in this research depends on a simple matrix made up of the upper and lower bounds for each of the different

COLS	NIM	80000000000000000000000000000000000000
COFS	XAM	20, 22, 25, 110, 10, 10, 10, 10, 10, 10, 10, 10, 1
THƏIN	NIW	ကိုက်ကိုလိုက်ကိုလိုလိုလိုလိုလိုလိုလိုလိုလိုလိုလိုလိုလိ
NIGHT	XAM	0,00,00,4,6,6,1,6,6,1,6,6,7,4,4,6,6,4,4,6,4,4,6,4,4,6,4,4,6,4,4,6,4,4,4,6,4,4,4,6,4,4,4,6,4
ЯАС	NIW	-, v, v, -, v, v, v, 4, L, v, 4, L, v, b, &, v, e,
ЯAS	XAM	ည့် ရှင်္သည် လူတိုင်္သည် အမောင်္သည် လူတိုင်္သည် လူတိုင်္သည် မောင်္သည် လူတိုင်္သည် လူတိုင်္သည် လူတိုင်္သည် လူတိုင်္သည်
TBOA	NIW	0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,
TBDA	XAM	00,0000
VAM	NIW	ယ်ယုံလုံကိုက်လုံလုံကိုနှံတို့ကိုနှံတိုလုံတို့ ထိုလ်တို့ ကိုကို တို့လို
VAM	XAM	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
TAS	NIW	ည် နှင့် လို့ လို
TAS	XAM	9,5,5,9,5,5,9,5,5,9,5,5,5,5,5,5,5,5,5,5
MD	NIW	4,6,4,6,6,4,6,6,4,7,7,7,7,7,7,7,7,7,7,7,
MD	XAM	8,0,1,8,0,1,9,0,7,7,9,0,0,6,9,7,5,7,5,7,5,7,5,7,5,7,5,7,5,7,5,7,7,5,7
SORTIE	NIW	46 55 55 55 55 55 55 55 55 55 55 55 55 55
SORTIE	XAM	55 27 28 39 20 20 20 20 20 20 20 20 20 20 20 20 20

TABLE Entry	TNG CTGRY	NEXT STATUS	MONTHS TO COMP	P1L0T CTGRY	PILOT STATUS	IP	EXPER	GCC LEVEL
_	CT			STAFF	Æ	YES	EXP	¥
2	C			STAFF	Æ	YES	EXP	8
က	CT			STAFF	꽃	YES	EXP	ပ
4	C.			STAFF	Æ	2	EXP	4
S	C1			STAFF	¥	9 N	EXP	8
9	ct			STAFF	뜻	9 9	EXP	ပ
7	CT			STAFF	₹	ջ	EXP	
æ	C1			PRIM	₹	YES	EXP	⋖
6	CT			PRIM	Æ	YES	EXP	8
2	CI			PRIM	Æ	YES	EXP	ပ
=	CI			PRIM	Æ	9 9	EXP	V
12	ct			PRIM	쭢	2	EXP	8
13	C1			PRIM	Æ	% %	EXP	ပ
14	CI			PRIM	¥	9 2	INEXP	V
15	CT			PRIM	쮼	2	INEXP	8
J6	ರ			PRIM	Æ	9 9	INEXP	ပ
17	IQT/MQT	쥰						
18	IQT/MQT	Æ	_					
19	1QT/MQT	폿	2					
8	IQT/MQT	Æ	က					
73	IQT/MQT	æ	4					

Figure 4 Dimension Table Key

combinations possible for a squadron assigned to maintain GCC Level C and both NIGHT and SAR capabilities. This matrix is illustrated in Figure 3. Figure 4 shows a key to determine which rows of the matrix relate to which pilot characteristics. As training directives or local standards change, the only action required to update the program is to change the appropriate entry in the matrix to correspond to the new guidance.

Figure 5 illustrates the logic flow within the computer program. The required input data is requested by the program through a series of questions. The actual input data is checked and an error message printed when a discrepancy is noted. As the data is read into the program it is stored in various arrays or matrixes and then processed as required.

The program establishes the sizes of the pilot groups (I, II, III, IV, or V) based on cutpoints which are computed using preprogrammed percentages and the total number of pilots entered into the program. The size of the groups can be altered by changing the percentages stored in CUTPER.

Based on the inputs the program selects the appropriate row from the Dimension Table and saves the information for each pilot.

Based on the cutpoints the columns of the Dimension Table that are variable, are adjusted, and the results are again stored. Next, the pilots are reranked by a process whereby the maximum by sortic type of each pilot is compared with the minimum of the next lower pilot. If the lower pilot's minimum is larger than the first pilot's maximum the lower pilot is given a ranking of "O." This results in spaces in the ranking sequence which need to be corrected (i.e., 1, 0, 3, 4, 0, 6).

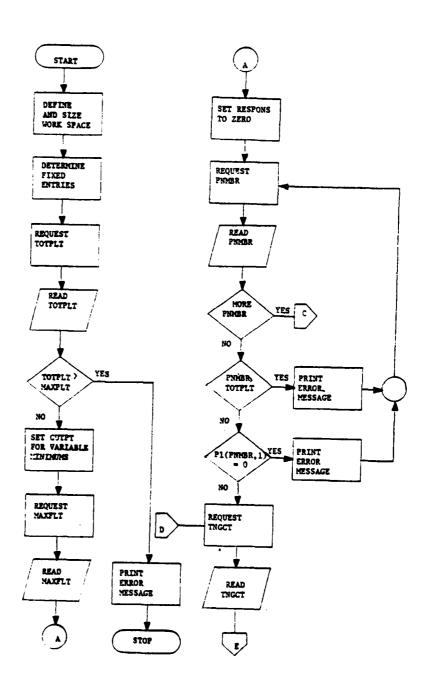


Figure 5
Flow Chart

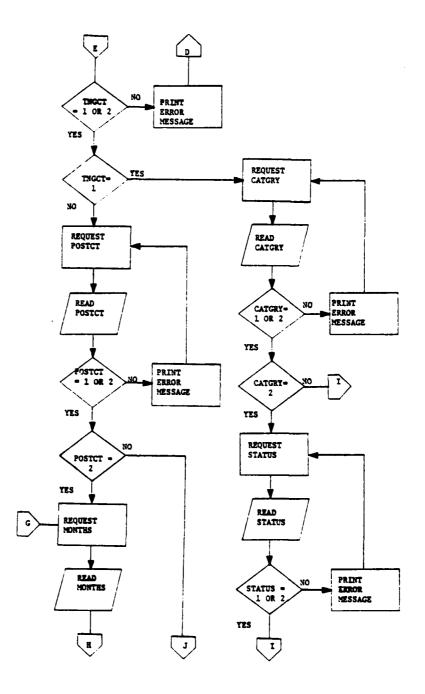


Figure 5 (Continued)

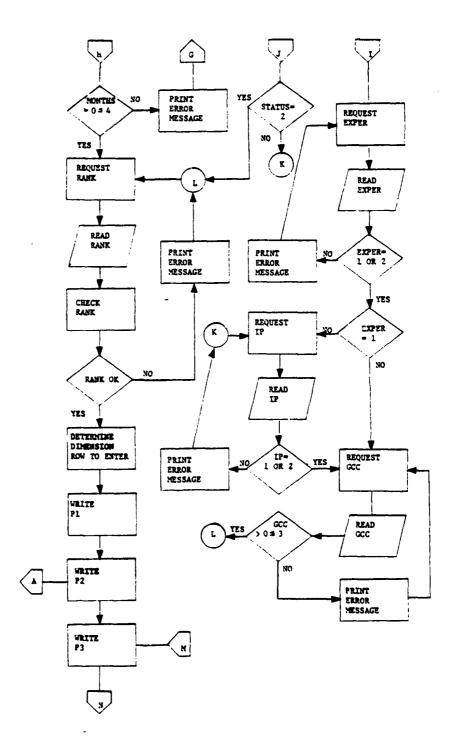


Figure 5 (Continued)

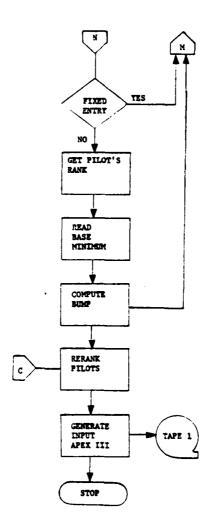


Figure 5 (Continued)

•

The nonzero entries are renumbered in sequence and the zero entries moved to the end of the matrix (i.e., 1, 2, 3, 4, 0, 0). This process was used to establish the constraint that a pilot should fly fewer sorties than the next lower ranked pilot unless this condition is not feasible due to other considerations (assignment of different GCC levels, mission status, or training category).

The final step in the program is to convert the input data into the proper format for the software package used (in this instance the CDC APEX III package).* The CARDS subroutine accomplishes this task by reading the processed data and generating an output in the general format depicted in Figure 6 on page 45. If a different input format is required for use with other linear programming software packages, the CARDS subroutine would have to be modified.

Further refinements are possible in the program by including additional error checks to make the system foolproof. Also, improvements would be made by adding loops to account for prorating pilots who are not available to fly during the entire training cycle or who are not tasked for both night and/or SAR requirements. Decision on what added capabilities are to be included in follow-on programs should be based on user needs and desires.

Although the original intent of developing the LP model was to minimize the sorties flown, the form of the objective function

^{*}The CDC APEX III package is an optimization program which provides a flexible approach to solving linear or integer programming models. Both the input and output formats used are standardized throughout the computer industry for this type problem. The size of the LP problem which the system can solve is normally limited by the amount of central memory accessible (i.e., 8,190 maximum constraints and 32,760 variables).

					- -S		
HAME	PANNELL				45	T#J	100
÷0±S	•				445	TSAT	100
L TeO					#MS	TMAV	100
L TSAT					##\$	TACBT	100
LIMAV					4≒5	TSAR	100
L TACAT					2HS	TNIGHT	100
L TSAH					##S	TCULS	100
LINIGHT					2H\$	P01	5 5
L TCOLS					4MS	ح و د	77
DN TOTALS	TWD	1.	TSAT	1.	~ANGES		
ON TOTALS	THAV	i.	TACST	1.	PANGES	01ء	•
ON TOTALS	ISAR	1.	ThiomT	1.	ZANGES	202	13
ON TOTALS	rculs	1.			SUNUS		
201					UI BOUNDS	-0140	11
202 ي					LI BOUNDS	P0140	10
COLUMNS					SUNUOF ID	POISAT	12
ري <u>د 1</u> 04	ن•1	1.	ن د د	1.	L: BOUNDS	POISAT	- 5
POISAT	TSAT	1.	FUI	1.	UI BOUNDS	POIMAV	¥
701 mav	TMAV	1.	- ∪1 '	ì.	LI dOUNUS	POIMAV	7
JOIMAN	COSULMAV	-i.			JI SUNUS	POLACET	7
POIMAN	COLUSMAV	1.			L! BOUNDS	POLACHT	6
POLACET	TACHT	1.	≟où	i.	SCHUOE 10	2015-2	Ÿ
⊃0!27∺	TSAR	1.	201	ì.	LI SOUNUS	201522	÷
PULNIGHT	INIGHT	i.	201	1.	ZUNUOE IU	POINTGET	16
POICULS	TCOLS		2 01	ì.	LI HOUNDS	POINIGHT	Š
ندوند	Teŭ	i.	2:2	1.	UI SOUNDS	POICOLS	11
ن≈20 د	C9502#0	-1.			LI BUUNUS	POICULS	7
202541	15±1	i.	2ن2	- 1.	JI JOUNUS	202WD	16
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202-AV	VAMSOLOS	-i.			LI SUUNUS	P02541	1 •
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Figure 6
LP Input

Note. Input data is divided into five sections: ROWS, COLUMNS, RHS, RANGES, and BOUNDS. The ROWS section names each row and shows if the ROW ACTIVITY is to be less than, greater than, or equal to the RHS. The COLUMNS section names each column and indicates the nonzero quantities. The RHS section names the right hand side(s) and shows the nonzero quantities. The RANGES section specifies the difference between the upper and lower limits of ROW ACTIVITY. The BOUNDS section specifies the upper and lower limits for the columns.

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makes it possible to run both a maximum and minimum solution to provide the scheduler with more information and a better basis for decision making. The next section provides a discussion of the computer solutions and the information available.

Computer Solution

The computer solution consists of two divisions, the first containing the minimum solution and the second containing the maximum solution. The minimum and maximum divisions are further divided into two sections. The first section, labeled CONSTRAINTS, depicts information on the rows of the solution matrix (listing of total sorties by type and by pilot). The second section, labeled COLUMNS, depicts the information on the columns of the solution matrix (listing by pilot of the number of each type sortie).

The CONSTRAINTS section is further divided into nine columns. These columns are labeled NUMBER, NAME, TYPE, STATUS, ROW ACTIVITY, SLACK, RHS LOWER, RHS UPPER, and MARGINAL.

NUMBER. The entries under this column are all integers. The integers represent the input order for the row.

NAME. The alphanumerics in this column are the row names. The names may be in one of three forms:

> TWD (Total WD sorties)

P01 (Total sorties for pilot 1)

C1416WD (Constraint on relationship between pilot

14 and pilot 16 ND sorties)

TYPE. Entries in this column indicate the nature of the relationship involved in the LP model. The possible entires include:

> EQ (Equals)

GE (Greater than or equal)

LE (Less than or equal) FR

(Free range from -∞ to +∞)

**

(An alternate optimal solution exists)

If a row is ranged a B will precede the above designators.*

STATUS. Indicates the basis status of the slack variable..** Entries are:

BINDING

(Either there is no slack, or this is a basis status of nonbasic or nonbasic at a bound)

SLACK

(There is slack or unused resources. This is a basis status of basic)

ROW ACTIVITY. The sum of the row activity (solution).

SLACK. The value of the difference between the right hand side (RHS) value input and the current ROW ACTIVITY (solution).

RHS LOWER. The minimum value the row sum can have.

RHS UPPER. The maximum value the row sum can have.

^{*}Ranging applies to row (constraints) of the problem and is a positive number which sets the allowable deviation from the RHS value. It serves the same purpose for rows that upper and lower bounds serve for columns.

^{**}Using a simplex tableau made up of a system of m equations and n variables, where m is less than n, let the excess variables (n-m) be assigned a value of zero. Then the remaining m equations in m variables have a unique solution such that:

⁽¹⁾ The variables (n-m) assigned a zero value are said to be "nonbasic."

⁽²⁾ The remaining variables (m) are called "basic."

⁽³⁾ The solution to the tableau is called a "basic solution." (5: 227-228)

MARGINAL. The shadow price of the row. The value indicates the change in the objective function for a change of one unit in the row. The sign of the MARGINAL value indicates if the objective function will increase or decrease when the row is changed by one unit. If the sign is positive the objective function will worsen and if negative the objective function will be improved.

If the ROW ACTIVITY is less than the RHS LOWER value or greater than the RHS UPPER value, the word INFEASIBLE will be printed on the extreme right hand side of the solution indicating a shortage of sorties. Either additional sorties will have to be made available or a less than optimal sortie allocation will have to be accepted. If the MARGINAL entry is nonzero in value and has an improper sign for the row TYPE and STATUS, the word NONOPTIMAL will be printed on the extreme right hand side of the solution indicating a better solution would be possible if the appropriate bound were changed. No action is required.

The COLUMNS section is divided into nine columns also. These columns are labeled NUMBER, NAME, TYPE, STATUS, COL ACTIVITY, OBJ COEF, BND LOWER, BND UPPER, and MARGINAL.

NUMBER. The integers in this column are the input order of the column entries.

NAME. The alphanumerics in this column are the names given to the columns. The names are in the form

POIWD (WD sorties allocated to pilot 1)

TYPE. Entries in this column indicate the column relationships.

Possible entries include:

PL	(Plus	variable
• •	(TWI IUDIC

MI (Minus variable)

FX (Fixed variable)

FR (Free variable)

BV (Bivalent variable; can be either 1 or 0)

INT (Integer variable)

** (Indicates other optimal solutions exist)

For ranged variables a B will precede the above designators.

STATUS. Entries in this column show the basis status of the column. The status can be:

ACTIVE (Column is basic)

UPPER (Nonbasic variable at its greatest value)

LOWER (Nonbasic variable at its smallest value)

COL ACTIVITY. The value in this column is the column activity level or current solution.

OBJ COEF. Entries in this column give the value of the objective column coefficient. For this solution the value will always be one.

BND LOWER. The smallest value the variable can have.

BND UPPER. The largest value the variable can have.

MARGINAL. The reduced or shadow cost of the variable.

If the value of the COL ACTIVITY is less than BND LOWER or more than BND UPPER the word INFEASIBLE will be printed on the extreme right hand side of the solution. If the MARGINAL value is nonzero and has an

improper sign for the column, the word NONOPTIMAL is printed on the extreme right hand side of the solution.

A review of some specific examples will help to explain how to interpret the data. To do this notional examples will be used for NUMBER entries 5(TSAR), 12(PO4), and 48(CO932WD) of the CONSTRAINTS section and NUMBER entry 204(P30WD) of the COLUMNS section.

Column	Entry	Meaning
NUMBER	5	TSAR was input number five to program.
NAME	TSAR	Total SAR sorties.
TYPE	LE	Constraint is less than or equal relationship.
STATUS	SLACK	Row sum not equal to RHS UPPER value.
ROW ACTIVITY	355	Total SAR sorties needed for feasible solution.
SLACK	-42	ROW ACTIVITY exceeds RHS UPPER by 42 sorties. Need 42 more SAR sorties for a feasible solution.
RHS LOWER	-INF	Since no bound was specified a -∞ lower limit is implied.
RHS UPPER	313	Initial SAR sorties for planning.
MARGINAL	•	If no value is entered the value is assumed to be zero. The shadow cost is zero.

The word INFEASIBLE printed at the right hand side indicates ROW ACTIVITY value is greater than RHS UPPER value. Forty-two more SAR sorties would be needed for the solution to be feasible.

The original constraints for the maximum and minimum number of sorties pilot 4 (PO4) could fly were:

 $X0401+X0402+X0403+X0404+X0405+X0406+X0407 \le 97$ and $X0401+X0402+X0403+X0404+X0405+X0406+X0407 \ge 83$.

These conditions are reflected in the entries in the nine columns of the CONSTRAINTS section as:

Column	Entry	Meaning
NUMBER	12	PO4 was number twelve input to program.
NAME	P04	Total sorties for pilot 4 (PO4).
TYPE	BLE	Relationship is a ranged less than or equal constraint.
STATUS	BINDING	Basis status at RHS LOWER value.
ROW ACTIVITY	83	Total sorties allocated to PO4.
SLACK	14	Difference between RHS UPPER and ROW ACTIVITY values.
RHS LOWER	83	Minimum sorties for PO4.
RHS UPPER	97	Maximum sorties for PO4.
MARGINAL	- 4	If the number of sorties allocated to PO4 was increased the objective function value would increase by 4.

To understand the entries for CO932WD it is necessary to examine the ranking process and the constraint that a pilot should not get more sorties than the pilots ranked lower than him in that type of sortie. For the basic solution, the following conditions were formulated:

Pilot Number	WD Ranking	Lower-Upper Bounds
P09	3	7 - 12
P32	4	12 - 16

For the constraints to hold, if PO9WD equaled 12 then P32WD would have to be 12 or more. The difference between PO9WD and P32WD would be the slack. Since PO9WD is required to be larger or equal to P32WD, the slack must have a negative sign. These conditions are reflected in the entries in the nine columns of the CONSTRAINTS section as:

Column	Entry	Meaning
NUMBER	48	Input was number 48 to program.
NAME	C0932WD	Constraint between PO9WD (XO901) and P32WD (X3201).
TYPE	LE	P09WD < P32WD.
STATUS	SLACK	There is a difference between PO9WD and P32WD.
ROW ACTIVITY	r -2	PO9WD is 2 units less than P32WD.
SLACK	2	Difference between RHS UPPER and ROW ACTIVITY is 2.
RHS LOWER	-INF	Since no lower limit was stated, $-\infty$ is implied.
RHS UPPER	•	Since PO9WD is not allowed to be greater than P32WD the maximum value is 0 when the two values are equal.
MARGINAL	•	The shadow value is 0.

From the COLUMNS section the value for PO9WD is 11 and for P32WD is 13. Therefore, the slack between PO9WD and P32WD is 2.

The final entry to be reviewed is the restriction on P30WD sorties. The original constraints were:

 $X3001 \leq 15$

X3001 > 9

These conditions are reflected in the entries in the columns of the COLUMNS section as:

Co1umn	Entry	Meaning
NUMBER	204	Input was number 204 to program.
NAME	P30WD	Total WD sorties for pilot 30 (P30).
TYPE	INT	Integer variable.
STATUS	**UPPER	Other optimal solutions exist. Solution is BND UPPER value.
COL ACTIVITY	15	Solution for number of WD sorties allocated to pilot P30.
OBJ COEF	1	Coefficients of WD variables are equal to 1.
BND LOWER	9	Minimum WD sorties for P30.
BND UPPER	15	Maximum WD sorties for P30.
MARGINAL	•	In the current solution there is no reduced costs for variable (X3001).

This chapter has presented an outline of the basic composition of the FORTRAN computer assisted scheduling program and the computer solution print-out. The intent was to familiarize the reader with how the system works and the information available. For a general guide on how to use the system see Appendix G.

Chapter IV

ANALYSIS AND CONCLUSIONS

Resource allocation problems lend themselves to mathematical optimization techniques. This is natural since there exists an objective or goal and various restrictions or constraints. There are both disadvantages and advantages to the application of mathematical techniques in assisting or accomplishing aircrew scheduling.

Disadvantages include the determination of optimality of the schedule generated and the formulation of the numerous constraints and decision variables. Another lesser difficulty could be an inability to quickly modify the basic computer program in the field to account for changes in scheduling priorities as they occur. This problem exists because there are no computer programmers readily available in the field to perform the required modifications. Probably the most limiting factor in the approach presented in this study is the need to rank pilots according to their individual proficiency in different types of sorties. My experience has been that pilots do not like to be ranked against their peers and would be concerned with the other possible uses of such rankings (job selection, OERs, etc.). Further limitations arise since objective measurement systems do not currently exist in some of the areas to provide a measure of individual pilot proficiency.*

^{*}Development of objective measurements of training programs is a subject of continued interest of Headquarters TAC Standardization/ Evaluation and is listed as a research topic in the 1979-80 volume of the Air University Compedium of Research Topics.

The advantages of this approach to resource allocation are considerable. Once the basic constraints are identified and expressed in mathematic relationships a linear model can be developed and solved by one of the many LP software packages which are readily available. Flexibility of the system depends primarily on the number of considerations taken into account when developing the basic program. The input program developed for this research clearly indicates the ease with which an interactive program can be produced which will be easy for any scheduler to employ without detailed training in computer languages. The ease with which various combinations can be generated and compared should lead to considerable time savings for the scheduler. Ultimately, the greatest advantage should be the efficient allocation of available training sorties to those who need them the most resulting in a unit with the highest overall proficiency or readiness.

The specific approach studied in this research should prove to be a valuable management tool. The approach can accurately project the training resources needed. It can be used to project requirements by total sorties, total sorties by type, and sorties both total and type for each pilot. In addition, by using both minimum and maximum solutions a range or "delta" for various sortie needs can be forecast. If this approach were combined with a system for prioritizing pilots for flight requirements based on qualification status, currency, quantity of sorties needed, and availability a very powerful computer assisted scheduling program could be generated.

Further research should be directed at the use of linear programming models in computer assisted scheduling modes. As the current

TAFTRAMS is changed from a batch system to an interactive system in the 1982 time frame the use of a system similar to the one developed in this research could be of considerable aid to the scheduler.* The next logical step would be to introduce the use of a goal programming approach into the scheduling process to allow for introduction of a priority goal system.

The current Burroughs Medium Computer system used by TAC was designed primarily for business applications. The system was not designed to perform high level arithmetic or scientific functions. However, the systems can perform these two functions when modified with a floating point adapter. This is a major drawback to implementing the program developed in this research due to the cost of the modification.

Another drawback to using the FORTRAN computer assisted scheduling program is the need for a FORTRAN compiler when using FORTRAN programs. This drawback can be overcome without any additional cost by using the available compilers and rewriting the program in the COBOL language or any other language compatible with the existing compilers.**

The availability of an LP software package which could be used in place of the CDC APEX III package is another area of concern.

Burroughs markets a software package named TEMPO. This package is a

^{*}Conversion of TAFTRAMS to an interactive AFORMS system in the 1982 time frame was confirmed as a goal in a conversation with Captain Andy Dorman from TAC DOOTR.

^{**}A compiler is an input device for translating programming languages into a machine language used by the computer for processing.

mathematical programming system which provides a capability similar to the CDC APEX III system. The input and output formats used by both systems are essentially the same. It would take only minor modification to make the FORTRAN computer assisted scheduling program compatible with the Burroughs' TEMPO system.

The major factor remaining then is cost. There are at least four options which could be followed to allow the scheduler access to this type of scheduling assistance each with differing costs. The options are:

- l. Modify all existing Burroughs medium systems with the floating point adapter and buy or lease the TEMPO package for each wing size unit.
- 2. Modify one system at Headquarters TAC, buy or lease the TEMPO package, and provide access to the units assigned to TAC.
- 3. Develop a suitable integer programming model using TAC resources and modify either one or all of the medium systems with floating point adapters.
- 4. Purchase a minicomputer for each wing size unit and develop a compatible integer programming software package.

To determine which option is most desirable in terms of a cost/benefit ratio additional analysis would be required at the time implementation of the program is contemplated.

The basic conclusion derived from this research is that while the application of LP models to aircrew scheduling can improve the efficiency of sortic allocation such a system cannot be currently implemented. Additional research will be required to determine the best

method to overcome the existing obstacles so that the benefits to be gained from this application can be realized.

Chapter V

SUMMARY AND RECOMMENDATIONS

The thesis of this research was that linear programming could be used to improve aircrew scheduling procedures by providing an efficient means of allocating available training resources to meet applicable training directives and the proficiency of individual pilots. To evaluate this thesis an imaginary A-7D squadron was established to provide the framework on which to build a mathematical model. The model was created using the general format applicable to linear programming models.

To simplify the transition from the linear programming model to a document which the scheduler could use for sortic allocation, a FORTRAN computer assisted scheduling program was written. This program was set up so that a detailed knowledge of computer programming was unnecessary. Indeed, all the scheduler is required to do is answer questions generated by the program and then tie the program to a computer software package for solving linear programming models.

Evaluation of the computer product indicated significant benefits to be gained in better use of available training resources. No apparent contradictions could be found with the computer product and applicable directives.

Research into the capabilities of the current computer capability possessed by TAC units indicates a degree of modification would

be needed before implementation of the program generated for this research could become a reality. However, the current Burroughs Medium System computer family can be used to perform the higher mathematics involved by addition of a floating point adapter. Furthermore, Burroughs has a current computer software package called TEMPO for the medium system computers which will provide the required LP model solving capability.

The feasibility of using linear programming and computer techniques to assist the scheduler in efficiently allocating training sorties has been adequately demonstrated. However, additional research will be involved before the system can be fielded. Additional work must be accomplished on developing meaningful programs to measure aircrew proficiency so that a suitable ability will exist to objectively rank pilots in the variety of sortie types flown. Also, research will be needed to determine if the cost/benefit ratio is great enough to justify the funds to support conversion of current systems to allow higher mathematical operations. If research into these two areas is positive, then actions should be taken to implement this or a similar follow-on program to assist the scheduler in using our ever dwindling training resources more efficiently.

APPENDIX A

APPENDIX A

DEFINITIONS AND ABBREVIATIONS*

<u>Air-to-Air Refueling (AAR)</u>. An event requiring hookup and transfer of fuel between two aircraft in-flight.

<u>Air Combat Maneuver (ACM)</u>. Coordinated application of BFM by two or more aircraft to achieve a simulated kill against one or more target aircraft from a preplanned and "canned" position.

<u>Air Combat Tactics (ACT)</u>. Application of ACM skills to achieve a tactical air-to-air objective under realistic scenarios.

Air Combat Training (ACBT). A generic term which inclues BFM/DBFM, ACM/DACM, ACT/DACT, and DCM where tasked in GCC training.

<u>Air Reserve Forces (ARF)</u>. Any of units assigned to the components of the United States Air Force Reserves.

<u>Air Support Tactics (AST)</u>. Close air support and air support training missions flown against targets identified by the battlefield commander. <u>Air-to-Surface Training (A/S)</u>. Training which consists of weapons delivery and surface attack sorties.

<u>Basic Fighter Maneuvers (BFM)</u>. Basic application of skills in roll, turn, and acceleration singularly or in combination toward one versus one aircraft positioning.

<u>Collateral Sorties (COLS)</u>. Sorties in addition to GCC requirements programmed to account for non-effective sorties and training required by Air Force requirements.

<u>Continuation Training (CT)</u>. Training flown by MR/MS aircrews to maintain proficiency and meet training requirements.

<u>Dissimilar Air Combat Maneuvers (DACM)</u>. ACM flown against one or more aircraft of a different design or series.

<u>Dissimilar Air Combat Tactics (DACT)</u>. ACT flown against one or more aggressor aircraft of a different design or series.

<u>Dive Bomb (DB)</u>. Delivery of ordnance off an aircraft from a dive angle of thirty degrees or more.

<u>Dissimilar Counter Maneuvering (DCM)</u>. BFM flown to negate an air-to-air attack and safely disengage.

<u>Graduated Combat Capability (GCC)</u>. A three level concept of managing resources against training requirements.

<u>Instructor Pilot (IP)</u>. A pilot selected because of his high experience level and mature judgement to train other pilots.

<u>Initial Qualification Training (IQT)</u>. Training flown before a pilot takes his proficiency checkride and enters MQT.

<u>Interdiction Tactics (IT)</u>. Tactical sorties flown on interdiction profiles emphasizing employment against preplanned targets.

<u>Low Angle Bomb (LAB)</u>. Delivery of a high drag weapon from a dive angle of less than twenty degrees.

Low Angle Low Drag Bomb (LALD). Delivery of a low drag weapon with a dive angle between twenty and thirty degrees.

Low Angle Strafe (LAS). Delivery of 20/30 mm ordnance on a surface target with a dive angle of less than twenty degrees.

<u>Mission Qualification Training (MQT)</u>. Training following IQT which prepares aircrews for their initial qualification checkride and entry into CT.

Mission Ready (MR). Status of an aircrew who meets GCC training requirements. The aircrew could enter into combat without further training.

Mission Support (MS). Status of an aircrew who flys the unit aircraft in support duties. An MS pilot requires further training prior to entry into combat.

<u>Search and Rescue (SAR)</u>. Locating and recovering downed aircrews in time of war.

Sortie. One flight from take-off to final landing.

<u>Standardization/Evaluation Flight Examiner (SEFE)</u>. An IP who is designated to perform aircrew flight evaluations in accordance with the Standardization/Evaluation Program.

<u>Visual Low Level Navigation</u>. A navigation flight flown at or below 1500 feet above the ground on a preplanned route.

<u>Weapons Delivery (WD)</u>. Expenditure of munitions against a surface target.

^{*}The definitions in this glossary are extracted from TACM 51-50 and the United States Air Force Dictionary.

APPENDIX B

APPENDIX B

MATHEMATICAL OVERVIEW

To understand the procedures developed in Chapter II, a general knowledge of linear programming techniques is needed. To provide the basic level of information necessary, the basic concepts are reviewed in this appendix. In addition, an introduction is provided to both dynamic and goal programming.

Linear Programming

Linear programming is based on the assumption that a decision maker desires to either maximize something (to make a value as large as possible) or minimize something (to make a value as small as possible). (5:212) The something which is to be maximized or minimized is called the objective function. The objective function is made of two or more variables to which the decision maker can assign values. Variables which can be assigned values by the decision maker and which affect the objective are labeled structural or decision variables. A list of variables with assigned values is called a program or solution.

For the decision maker to develop an optimal program he must identify the relationship existing between the objective and the structural variables. In addition to the objective function, mathematical models are based on the assumption that the decision maker is faced with restrictions on the values which the structural variables can be assigned. These restrictions include limited resources, technical requirements, or other obligations.

Restrictions are included in mathematical models by introducing constraints. A constraint is a relationship that limits the values a structural variable can be assigned. Constraints can be expressed in terms of three propositions. The propositions are (1) equal to, (2) greater than, and (3) less than.

To understand how an optimal solution is obtained, one must know the difference between feasible, infeasible, and optimal programs. A feasible program is one which meets all of the constraints of the mathematical model, whereas an infeasible program violates one or more of the constraints. An optimal program is one which is feasible and either maximizes or minimizes the objective function.

Underlying linear programming is the proposition that the objective function and all the constraints are linear relations and that the structural variables are nonnegative. These considerations can be expressed mathematically as follows:

1. The objective function is expressed as

$$f(z) = a_1x_1+a_2x_2+a_3x_3+ \dots +a_nx_n$$

where a_1 , a_2 , a_3 , ..., a_n are real-valued constants.

2. Each constraint is expressed as

$$b_1x_1+b_2x_2+b_3x_3+ \dots +b_nx_n = C$$
, or $b_1x_1+b_2x_2+b_3x_3+ \dots +b_nx_n \ge C$, or $b_1x_1+b_2x_2+b_3x_3+ \dots +b_nx_n \le C$,

where b_1 , b_2 , b_3 , ..., b_n are real-valued constants.

3. The structural variables x_1 , x_2 , x_3 , ..., x_n are real-valued variables. (2:1)

Simple linear programming models of two variables can be solved manually by using graphical techniques. Linear models which have more than two variables require using nongraphical techniques such as the simplex algorithm. The use of the simplex algorithm technique becomes very tedious as the number of variables increase. Computer manufacturers or company vendors offer computer programs (software) for solving linear programming models. The use of these programs facilitates the solution of linear models and provides the user a number of means for post-optimal solution analysis. (2:144) The ability to perform post-optimal solution analysis allows an evaluation of the effects of changes in any of the constraints which define the problem.

Dynamic Programming

Dynamic programming is a valuable technique when faced with multistage or time related decision processes (processes involving multiple interrelated choices). Multistage decision processes are thought of as being made up of policy choices, stages, states, and objectives. (5:Ch 10)

Policy Choice. A policy choice is a choice (decision) made at some point in a multistage decision process. Usually a policy choice is needed at each of the stages.

Stage. A stage is a set of feasible choices occurring at some point in a multistage decision process.

State. A state is a condition that influences a policy choice at a decision stage.

Objective. An objective is the goal to be attained by the policy choice selected at each stage of the decision process.

In general, dynamic programming may be useful in instances where linear programming models are not feasible. Dynamic algorithms can be developed and computerized for use in solving complex problems with a great number of variables. While this technique is beneficial in solving multistage decision processes, it is by no means a panacea for solving all very large problems. If there are too many state variables at each stage, the amount of computer memory required for storage becomes excessive. The end result is that even very large computers may be unable to accommodate the memory needs of some dynamic programming algorithms.

Goal Programming

Goal programming is gaining in popularity as a technique for solution of problems with competing objectives. It is a relatively recent method which takes into account trade-offs between possible goals or objectives for the decision maker. It is a modification of linear programming which takes advantage of the slack variables to free the decision maker from a one dimensional objective function.*

It accomplishes this task by using the slack variables to minimize the deviations between goals that are set within the system of constraints for the problem.

The goals or objectives for the problem are stated and arranged in order of their priority. The algorithm used for the solution process successively seeks the achievement of these goals in priority, where the higher goals become constraints which must not be violated.

^{*}A slack is a variable used to show how much of a given resource was not used in a solution.

Therefore, higher goals are satisfied at the expense of the lower priority goals. This approach will let the decision maker meet as many of his needs as is feasible under the conditions which prevail for the problem.

APPENDIX C

APPENDIX C

VARIABLE LISTING

To read Table 13, read down column one, labeled pilot, to the pilot number desired. Then to determine the variable designation for a specific type sortie move to the right along the same row to where it intersects with the desired column. For example, the variable representing the number of weapons delivery sorties flown by pilot 10 (P10) would be X1001.

TABLE 13 Variables

พอ (01)	SAT (02)	MAV (03)	ACBT (04)	SAR (05)	NIGHT (06)	COLS (07)
X0101	X0102	X0103	X0104	X0105	X0106	X0107
X0201	X0202	X0203	X0204	X0205	X0206	X0207
X0301	X0302	X0303	X0304	X0305	X0306	X0307
X0401	X0402	X0403	X0404	X0405	X0406	X0407
X0501	X0502	X0503	X0504	X0505	X0506	X0507
X0601	X0602	X0603	X0604	X0605	X0606	X0607
X0701	X0702	X0703	X0704	X0705	X0706	X0707
X0801	X0802	X0803	X0804	X0805	X0806	X0307
X0901	X0902	X0903	X0904	X0905	X0906	X0907
X1001	X1002	X1003	X1004	X1005	X1006	X1007
X1101	X1102	X1103	X1104	X1105	X1106	X1107
X1 20 1	X1202	X1203	X1204	X1 205	X1206	X1207
X1 301	X1302	X1303	X1 304	X1 305	X1306	X1 30 7
X1401	X1402	X1403	X1404	X1405	X1406	X1407
X1501	X1502	X1503	X1504	X1505	X1506	X1507
X1601	X1602	X1603	X1604	X1605	X1606	X1607
X1701	X1702	X1703	X1704	X1705	X1 706	X1707
X1801	X1802	X1803	X1804	X1805	X1806	X1807
X1901	X1902	X1903	X1904	X1905	X1906	X1907
X2001	X2002	X2003	X2004	X2005	X2006	X2007
X2101	X2102	X2103	X2104	X2105	X2106	X2107
	X0101 X0201 X0201 X0301 X0401 X0501 X0601 X0701 X0801 X1001 X1101 X1201 X1301 X1401 X1501 X1501 X1801 X1901 X2001	X0101 X0102 X0201 X0202 X0301 X0302 X0401 X0402 X0501 X0502 X0601 X0602 X0701 X0702 X0801 X0802 X0901 X0902 X1001 X1002 X1101 X1102 X1201 X1202 X1301 X1302 X1401 X1402 X1501 X1502 X1601 X1602 X1701 X1702 X1801 X1802 X1901 X1902 X2001 X2002	(01) (02) (03) X0101 X0102 X0103 X0201 X0202 X0203 X0301 X0302 X0303 X0401 X0402 X0403 X0501 X0502 X0503 X0601 X0602 X0603 X0701 X0702 X0703 X0801 X0802 X0803 X0901 X0902 X0903 X1001 X1002 X1003 X1101 X1102 X1103 X1201 X1202 X1203 X1301 X1302 X1303 X1401 X1402 X1403 X1501 X1502 X1503 X1601 X1602 X1603 X1701 X1702 X1703 X1801 X1802 X1803 X1901 X1902 X1903 X2001 X2002 X2003	X0101 X0102 X0103 X0104 X0201 X0202 X0203 X0204 X0301 X0302 X0303 X0304 X0401 X0402 X0403 X0404 X0501 X0502 X0503 X0504 X0601 X0602 X0603 X0604 X0701 X0702 X0703 X0704 X0801 X0802 X0803 X0804 X0901 X0902 X0903 X0904 X1001 X1002 X1003 X1004 X1101 X1102 X1103 X1104 X1201 X1202 X1203 X1204 X1301 X1302 X1303 X1304 X1401 X1402 X1403 X1404 X1501 X1502 X1503 X1504 X1601 X1602 X1603 X1604 X1701 X1702 X1703 X1704 X1801 X1802 X1803 X1804 X1901 X1	X0101 X0102 X0103 X0104 X0105 X0201 X0202 X0203 X0204 X0205 X0301 X0302 X0303 X0304 X0305 X0401 X0402 X0403 X0404 X0405 X0501 X0502 X0503 X0504 X0505 X0601 X0602 X0603 X0604 X0605 X0701 X0702 X0703 X0704 X0705 X0801 X0802 X0803 X0804 X0805 X0901 X0902 X0903 X0904 X0905 X1001 X1002 X1003 X1004 X1005 X1101 X1102 X1103 X1104 X1105 X1201 X1202 X1203 X1204 X1205 X1301 X1302 X1303 X1304 X1305 X1401 X1402 X1403 X1404 X1405 X1501 X1502 X1503 X1504 X1505 X1601	(01) (02) (03) (04) (05) (06) X0101 X0102 X0103 X0104 X0105 X0106 X0201 X0202 X0203 X0204 X0205 X0206 X0301 X0302 X0303 X0304 X0305 X0306 X0401 X0402 X0403 X0404 X0405 X0406 X0501 X0502 X0503 X0504 X0505 X0506 X0601 X0602 X0603 X0604 X0605 X0606 X0701 X0702 X0703 X0704 X0705 X0706 X0801 X0802 X0803 X0804 X0805 X0806 X0901 X0902 X0903 X0904 X0905 X0906 X1001 X1102 X1103 X1104 X1105 X1106 X1201 X1202 X1203 X1204 X1205 X1206 X1301 X1302 X1303 X1304 X1305 X1306

TABLE 13 (Continued)

PILOT	WD (01)	SAT (02)	MAV (03)	ACBT (04)	SAR (05)	NIGHT (06)	COLS (07)
P22	X2201	X2202	X2203	X2204	X2205	X2206	X2207
P23	X2301	X2302	X2303	X2304	X2305	X2306	X2307
P24	X2401	X2402	X2403	X2404	X2405	X2406	X2407
P25	X2501	X2502	X2503	X2504	X2505	X2506	X2507
P26	X2601	X2602	X2603	X2604	X2605	X2606	X2607
P27	X2701	X2702	X2703	X2704	X2705	X2706	X2707
P28	X2801	X2802	X2803	X2804	X2805	X2806	X2807
P29	X2901	X2902	X2903	X2904	X2905	X2906	X2907
P30	X3001	X3002	X3003	X3004	X3005	X3006	X3007
P31	X3101	X3102	X3103	X3104	X3105	X3106	X3107
P32	X3201	X3202	X3203	X3204	X3205	X3206	X3207
P33	X3301	X3302	X3303	X3304	X3305	X3306	X3307
P34	X3401	X3402	X3403	X3404	X3405	X3406	X3407
P35	X3501	X3502	X3503	X3504	X3505	X3506	X3507
P36	X3601	X3602	X3603	X3604	X3605	X3606	X3607
P37	X3701	X3702	X3703	X3704	X3705	X3706	X3707

APPENDIX D

APPENDIX D

FORTRAN COMPUTER ASSISTED SCHEDULING PROGRAM

This appendix contains the program developed to generate the required input for the CDC APEX III LP software package. Although it is written in FORTRAN there is no reason it could not be converted to COBOL or another programming language.

```
BOUGRAM FILLP (INPUT.OUTPUT.TAPEL)
GENERATE ON TAPEL INPUT DATA SULTABLE FOR APEX LE PACKAGE
FOR PILOT TRAINING FLIGHT ASSIGNMENT PROBLEM
PI HOLDS THE INPUT CATEGORY DATA FUR EACH PILOT
P2 HOLDS DANKING DATA FOR EACH PILOT IN S SO-TIE TYPES
P3 HOLDS TOTAL AND SUNTIE TIPE MANYMIN FUR EACH PILOT
PNKRNK HOLDS FILOT MANKING IN PANK OF E-. THAT IS IF PILOT
WIMBER & IS MANKED FLAST FUR FLIGHT J. THEN RIKRIK (1. 1) #4.
CUTPER HOLDS CUTPOINT PERCENTAGES FOR SETTING VARIABLE MINS
    CURRENT VALUES WILL SPEAK INTO 10.20.40.20.10 & BRACKETS
CUTPY HOLDS CUTHOINIS BASED IN CUTPER AND NUMBER OF PILOTS TABLE CONTAINS TO VALUES FOR EACH PILOT CATEGORY ENTRY (CURRENTLY 21)
     VALUES ARE MAXIMIN FUR TOTAL . HU-SAT. MAY. AC-T. SAR. NIGHT. COLS
TINES SET THUE IF MIN VALUE FOR AN ESTAY DU NOT VARY
 MAXELT HULDS MAX ALLIMED TOTAL PER SOUTIE TIME
 RESPAS IS WORKING AREA FOR IMPUT DATA. MUVED TO PI AND PE
     IMPLICIT INTEGER (4-2)
     DIMENSION -1 (50+7) -22 (50+5) -23 (50+10)
     DIMENSION WARRANK (50.5)
     REAL CUTPER (4)
     DIMENSION TABLE (16.21)
     LOGICAL FIREUREL
     DIMENSION -ESPNS(14) . HANK (5) . MAAFLT (7)
     EQUIVALENCE (HESPNS(1) . PNMBR ) . (HESPNS(2) . TNGCAT) .
                     (-ESHNS(3) . PUSTCT) . (-ESHNS(-) . MONTHS) .
                    (HESHNS (S) . CATGRY) . (HESHNS (5) . STATUS) . (HESHNS (7) . IP ) . (HESHNS (8) . EXPER ) .
                                         1 . (455M15 (4) .cxPE4 ) .
                                        ) + ( 4E 3 M 75 ( LU ) + HANK ( L) )
                     (#ESMNS (7) +GCC
 CURRENTLY SET UP FOR AT MOST SO MILLUTS AND AL CATEGORIES
  APPROPRIATE ARRAY SIZES AND FOLLUATING UNTA STATEMENT SHOULD
 BE CHANGED TO CHANGE THESE VALUES.
  FULLOWING DATA STATEMENT SETS CUTPOINT PERCENTAGES
```

and a second control of the Mark

DATA CUTPER /.19..30..70..40/

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C FULLOWING SET UP THE MAXIMIN VALUES FOR IMPLIEUS PILOT CATEGORIES
       DATA ((TABLE(J.K).J=1.16).K=1.1J) /
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      1 55. 46. 4. -4. 71 -5.
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      2 72. 56. 10. -5. 12. -7.
                                                                    5. 21. 16.
                                                       ** -3. lu.
                                     *• -5•
                                             1. -2.
      3 #1. 75. 11. -6. 12. -5.
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                                                                    5. 62. 17.
                          9. -5.
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      4 42. 33.
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      6 65. 59. 11. -5. 12. -5.
7 39. 30. 5. 2. 10. 2.
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      6 50 - 40 - 41 -51
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                                    5. -u.
      9 51. 50. 12. -s. 12. -s.
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                                                                    2. 11. 10.
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      x 70. 09. 12. -7. 13. -8. 10. -0. 10. -0. 11. -7. 11.
                                                                            10 /
       DATA ((TABLE(J.K).J=1.16).K=1..20) /
                                                                    2, 25.
                                   7. -3.
     1 57, 49, 4, -5, 4, -5,
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                                                       0. -4.
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                                                                            12.
      2 70. 59. 12. -0. 12. -3.
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      3 89. 77. 12. -7. 13. -8. 13. -3.
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      4 50 · 36 · 13 · -6 · 12 · -3 · 5 · -2 · 5 · 71 · 59 · 10 · -6 · 13 · -5 · 10 · -6 ·
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      6 9/. 44. 16.-12. 18.-13. 12. -5. 12. -6. 10. -6. 15.
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      7 34. 30.
                  6. 2. 10. 2.
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   KEYS TO TABLE ENTRIES IN FOLLOWING LAYOUT
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C TABLE THE
                   NEXT
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TOMATEI
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```

لأبلا الخرارية مستوار سيتان سيتوارات

```
C
      CALL CONNEC (SLINPUT)
      CALL CONNEC (GLOUTPUT)
  DETERMINE AMICH ENTHIES WILL MAVE FIXED MINIMUMUMS
      AHINZHITEN OF OC
      S.51.4=# 01 00
      IF (TABLE (K.J) .LE.0) GO TO 20
10
      CONTINUE
      FIXED(J) =. TRUE.
      GO TO 50
٥٥
      FIXED(J) = . FALSE .
50
      CONTINUE
  MEAD TOTAL NUMBER PILLUTS. MAKE SURE ITS UNDER MAX SPACE.
      PRINT 1001
      JEAD .. TOTALT
      IF (TOTPLT.LE.MAXPLT) GO TO 70
      PPINT 2001 - MARPLT
      STOP
С
  SET UP CUTPOINTS TO BE USED FOR VARIABLE MINS
10
      00 80 J=1.4
50
      CUTPT (J) = CUTPER (J) = FLOAT (TOTPLT) = 0.5
  READ OVERALL MAX FLIGHTS BY TYPE
      2001 TP1P4
      READ .MAXFLT
  START INPUT FUR EACH PILOT. FIRST CLEAR OUT PESPONSE SPACE.
     00 101 J=1.14
iuu
ivi
     RESPNS (J) ≠ů
  FILOT NUMBER. NOT OVER TOTAL AND NOT ALREADY USED.
     PILOT NUMBER 499 FLAGS END OF IMPUT
103
     PGINT 1003
      SBEING. . CABE
      IF (PNMSH. 20. 494) GU TO 300
      IF (PNMSR.LE.TOTPLT) GO TO 10301
      PEINT 2002. TUTPLT
      50 TC 103
10301 IF (P1 (PNMHH+1) . Eu. U) GO TO 10-
      E002 TM164
      50 TO 103
  TRAINING CATEGORY--LECT.ZEIQT/MUT
```

```
POINT 1004
104
      READ . TNGCAT
      IF (TNGCAT.EQ.1 .UR.TNGCAT.EQ.2) GO TO 10-01
POINT 2000
GO TO 104
C JUMP FOR CT. STAY HERE FOR IJI/MQI
10-01 IF (TNGCAT.EU.1) GO TO 107
Č
  MAVE INT/MOT. GET CATEGORY AFTER ING--1=MR.2=MS
105
      POINT 1005
      PE40 .. POSTCT
       IF (POSTCT.EG.1 .UP. POSTCT.EG.2) GO TO 19501
      D005 14196
      GU TO 105
C GET MUNTHS FOR 4#.
10501 IF (POSTCT.EQ.2) GO TO 112
      PRINT 1005
READ + MUNTHS
106
       IF (MONTHS.JT.0 .AND. MONTHS.LE.4) 30 TO 112
      0005 TAIPS
       on to 106
   MAVE ING CATEGORY CT. GET PILOT CATEGORY--12PHIMARY. 2=STAFF
      PRINT 1007
i 07
      READ . CATGRY
       IFICATGRY.EG.1 .09. CATGRY.EG.2) GO TO 10/01
      DOOS THICE
       30 TO 107
  FUR PRIMARY STAY AND GET EXPERIE (CE-- 1 *EXP . C= INEXP
10701 IF (CATGRY.EQ.2) GO TO 109
      POINT 10UM
      PEAD .. EXPER
       IF (EXPERIEU.1 .UM.EXPERIED.2) OU TO LOBUL
POINT 2000
GO TO 109
C PICK UP IP STATE FOR EXPERIENCED.
10801 [F(EXPER.EJ.1) 60 TO 110
       30 TO 111
   MAVE A STAFF MILOT. DETERMINE STATUS--MURI. 45=2
109
       201NT 1000
       -EAD +.STATUS
       IF ($74TUS.20.1 .UF.STATUS.20.2) 50 TO 10401
      0005 171cc
GO TO 109
C SKIP TO PANKS IF MS.
10901 IF (STATUS. 20.2) GO TO 112
```

```
C IS PILOT IP?--I=YES.Z=NU
       PRINT 1010
110
       READ .IF
       IF (IP.EQ.) .UR. IP.EQ.2) 30 TO 111
       0005 TM1CG
       GO TO 110
C GCC LEVEL -- 1 = 4 . 2 = 7 . 3 = C
111
      PPINT 1011
      PEAD → GCC
IF(GCC.GT.0 .440.GCC.LE.3) GO (O 112
       DOUS TRIVE
       GO TO 111
   NOW GET THIS PILOTS HANKINGS BY FLIGHT TIPE
112
      201NT 1012
      READ .....
   CHANK INSURES LEGAL MANKS: SAVES THEM IN ACCOUNT.
WILL TAKE ALTERNATE RETURN IF CHORLEMS DETECTED.
CALL CHRANK (PNMBH-TOTPLT-MANK-MARNK-P2) -HETURNS(112)
   DETERMINE WHICH TABLE ENTRY TO USE
     NOTE THAT THIS LUGIC DEPENDS ON UNUSED SELECTION ITEMS
      BEING ZEHO TO WORK PROPERLY.
      ENIRYED
       IF (TNGCAT. NE. 1) GU TO 150
       IF (CATGRY.EQ.1) ENTRY=?
       IF (STATUS.EG.2) ENTRY=7
       IF (IP.EU.Z) ENTRY ENTRY -3
       IF (EXPER. 64.2) -NTHY #ENTRY +6
       ENTHY#ENTH + GCC
       GO TO 200
      ENTRY=17+-UNT-S
i50
   SAVE THIS PILUT'S DATA AND GET THE NEXT ENTRY
      P1 (PNYSH.1) HENTHY
200
       00 210 J=2.9
      PI (PHARR. J) = HESPNS (J)
       56 220 J=1.5
      P2 (PNMBR+J) #HANK (J)
220
       GO TO 100
   ALL DATA HAS SEEN INPUT. NOW SET UP REJUIRED VALUES
300
      DO 400 PILOT=1.TUTPLT
      ENTRYERI (PILUT-1)
      00 310 J=1.15
P3(PILOT-J)=[48LE(J+611F4Y)
310
```

```
IF MINS CANT PARY THAT IS ALL THAT IS NEEDED.
        IF (FIAED (ENTRY)) SO TO +00
    MINS CAN VA-Y . . . FIRST GET THIS PILITYS FANKING
        00 320 J=1.5
       (L.TCJI9)SH=(L) ANAR
320
    NUM FOR FIRST FIVE SORTIE TYPES PICK OF THE EASE MIN (WHICH IS A NEGATIVE) AND DECIDE HOW MUCH TO MUMP IT
      BASED ON WHERE THE MANKING HITS THE CUINCINTS.
        00 350 K=1.5
        PO[N[=2+(K+1)
        SASE=LASS (#3 (PILUT.POINT))
        00 330 J=1.4
        IF (WANK (K) . LE. CUTPT (J)) 50 TO 335
        CONTINUE
330
        125
335
        HIJMP#J-[
        P3 (PILOT.PUINT) #545E+5UMP
        CONTINUE
350
        CONTINUE
-Û0
   RERANK WILL TUSS DUT INFEASIBLE WANKINGS AND CLEAN UP THE
        RANKING ARRAYS AS NEEDED.
        CALL REMANK (TOTPLT.P2.-NKRNK.P3)
   CARDS GENERATES THE APEX INPUT ON TAPEL
        CALL CARDS (TUTPLI-MAXELT.P3.P2.PNK-NK)
C
        STOP
1001 FORMAT (" TOTAL NUMBER OF PILOTS ?")
1002 FORMAT(" MAX NUMBER OF #0.5AT. MAY. LCTT. SER. NIGHT. COLS SOFTIES".
      1 / . . ? . .
1003 FORMAT(" PILOT NUMBER-- (944 TO 570P) ?")
100% FORMAT(" TRAINING CATEGORY -- CTELLI, INMUTEZ ?")
1005 FORMAT(" CATEGORY AFTER TOTAMITE-M-ELIMBEZ ?")
1005 FORMAT(" MUNTHS TO COMPLETE LITAMITE-1-2-3 OF 2 ?")
1007 FORMAT(" PILOT CATEGORY---POIMENTEL.STAFFEZ ?")
1009 FORMATIN PILOT STATUS--MR=1.MS=2 ?")
LOTO FORMATIN IS PILLY AN IP-TES=1.40=2 (")
1008 FORMAT (" EXPENTENCED#1 . I VERPENTENCED#2 3")
1011 FORMAT(" 3CC LEVEL -- A=1 + d=2 + C=3 2")
1012 FORMAT(" PANKING FOR AC-SATEMAY + AC-T+ SAW SURTIES" + Z+M 2")
       FORMAT(" ILLEGAL ENTRY --- THY AGAIN")
FORMAT(" MAX PILUTS ALLOWED IS" ( In " MUST CHANGE PROGRAM")
FORMAT(" PILUT NUMBER CAN NOT BE 3-EATER THAN TOTAL OF" ( IN FORMAT(" OATA FOR THIS PILOT MOMBER ALREADY ENTERED")
2000
<001
2002
2003
        E . D
```

```
SUBROUTINE REPANKITOT .- ANK . HA . K 2 . M . X )
    WHERE PILOT PA IS HANKED "N" AND PILOT PH IS PAYKED "4-1" . WE
    DESINE THE CONSTRAINT THAT PA FLIGHTS HE LESS OR EQUAL PH FLIGHTS. THIS IS INFEASIBLE IF PHIS MAK IN LESS THAN MAIS MIN.
    PERANK CHECKS FOR INFEASIBILITIES OF
                                                         THIS NATURE AND. WHEN FOUND.
    MEMOVES PH FROM THE PANKING SCHEME.
         IMPLICIT INTEGER (4-Z)
        DIMENSION FANK (50.5) . HANKE (50.5)
        JIMENSIUN MAX (50 . 10)
C
        90 10 J=1.5
        00 10 K=1.TOF
        PLACE = PANK (K.J)
C10
         RANK2 (PLACE . J) =K
   LOOP 30 FIVE TIMES FOR THE FIVE SURTIE TYPES TO BE CHECKED.
   MARP AND MINP PUINT TO MAX AND MIN ENTRIES FOR THE SORTIE TYPE.

START WITH THE FILOT MAKED FIRST AS PAUND FILOT MANKED SECOND
AS PRIAND MAKE THE CHECK. IF FEASIBLE. THE SECOND PILOT BECOMES
PAUND THIRD MILOT BECOMES PRIAND SO ON TILL ALL ARE CHECKED.

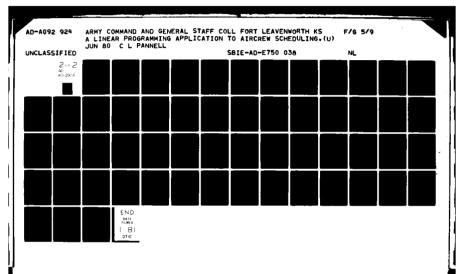
IF INFEASIBLE. PRIS UMORPED OUT (GIVEN A ZERU BANK). THE NEXT
HANKED PILOT IS MICKED UP AS PRIMOUTHE CHECK MADE AGAIN.
c
        00 30 J=1.5
         4TNPEMAXP+1
        24=1
         ~~ = 1
c0
         구뉴모유럽 - 1
         IF(98.GT.TOT) GO TO 30
         PARRINKZ (HA.J)
        PRERANK 2 (JAG. J)
   .LT. CHECK WOULD SUFFICE TO FIND INFEASIBILITIES
   24228
        GO TO 20
25
        -ANKS (88.1) =U
        PENK (PB+J) =0
        GU TO 20
        CUNTINUE
30
    NUM MUST CLEAN UP BANK ARMAY. SUPPOSE MILOT RANKED 3 MAS BEEN DYOPPED 4800E. ITAL MEANS BILUTS MANNED 40000 ETC. NUM SHOULD
    BE PANKEU 3.4.5. ETC. LOUP TO ACCOMPLISHES ITIS.
         JU 50 J=1+5
        PNK=1
         #4=1
+0
        PAERANKZ (RA.J)
        IF (P4.LE.0) 30 TO -5
        PANK (PA.J) ARNK
```

```
えったまえった・1
        44=8=+1
        IF (HA.LE.TOT) SU TO -0
        CONTINUE
   ALSO MUST CLEAN UP THE PILOT BY HANKS AHAMY. IF MILOTS WERE DROPPED ABOVE THIS ARMAY NOW HAS ZEPU ENTRIES. MUVE ALL NUNHZERO ENTRIES TO FRONT OF THE ARRAY AND ZEPU FILL AT END.
        00 HO J=1.5
        I Na l
        OuT=1
        IF (RANK2(IN-J) . EQ. 0) GO TO 75
70
        ICONI) SAMARE (LOTUO) SAMAR
        QUIT=QUT+1
15
        IN=IN+1
        IF (IN-LE-TOT) GO TO 70
        IF (OUT. ST. TOT) SO TO 40
        90 78 K=001+TUT
78
        2 mink 5 (K+J) = 0
÷0
        CONTINUE
        RETURN
        ENO
        SUBROUTINE CARDS (NPLT-MAXFLT-MAX-HANK-HANK2)
   GENERATE APEX INPUT DATA
        IMPLICIT INTEGER (A-Z)
        DIMENSIUM WANK (SU.S) . PANK 2 (SU.S)
        DIMENSION WAMES (7) . MAXELT (7)
        DIMENSION MAX (50 . 15)
C
        DATA STP /7/
        DATA NAMES /2mm0.3msat.3mmav.+mac3:.3msar.bmv1um1.+mcols /
    NAME MEADER AND YOWS SECTION
        40 ITE (1.2061)
2001 FORMAT ("NAME", TIS. "PANNELL", V. "WU#5")
C UNE WUW FOR EACH FLIGHT TYPE TOTAL
       DC 100 K=1.NIP
100
        w=ITE(1.2002) NAMES(F)
2002 FORMAT(5M L 1:43)
C OVERALL TOTAL IS LINEAR COMBINATION OF THE FLIGHT TYPE TOTALS
        20 110 K=1.NTP.2
        IF (K.EQ.NTP) 30 TO 111
        #PITE(1.2003) NAMES(K) . NAMES(K-1)
        GO TO 110
111
        #PITE(1+2004) NAMES(K)
110
       CONTINUE
COMMAT(" ON FOTALS"-TIS-"T"-AS-F25-"1."-TWO-"T"-AS-TSU-"1.")
COOK FORMAT(" ON TOTALS"-TIS-"T"-AS-T25-"1.")
CONE WOW FOR EACH PILOT TOTAL
```

```
90 120 J=1.NPLT
      ## [TE(1.2005) J
120
2005 FORMAT(" L P" . [2.2]
  CONSTRAINT HOWS BASED ON PILOT REMAINS FOR EACH FLIGHT TYPE
Ç
      JO 150 K=1.5
      DG 130 J#1.NFLT
      DI=HANKZ(J.K)
      PS=HANK2(J+1+K)
      IF (P2.LE.J) 50 TO 150
#PITE(1.21u1) P1.P2.NAMES(K)
130
      CONTINUE
150
2101 FORMATISH L C. 212.2.45)
   CULUMNS SECTION
       ##1TE(1.2006)
∠006
     FORMAT ("COLUMNS")
   ONE COLUMN FOR EACH PILOT/FLIGHT TYPE COMBINATION
      00 250 J=1.NPLT
00 240 K=1.NTP
C ENTERS INTO FLIGHT TYPE AND HILOT TYPE TOTALS
#RITE(1.2007) J.NAMES(K) .. MAMES(K) .. 2007 FORMAT(T5. "P" .. 12.2745.T15."T" .45. 125."1.".
      · [".1"+0cT+5.5]+"9"+u+1 •
C ENTER INTO PANKING CONSTRAINT, FLAST FIVE FLIGHT TYPES
       IF (K. 61.5) GO TO 240
       CUMPOSERANK (J+K)
       IF (CUMPOS.EN.D) GO TO 240
       POEVERANKS (CUPPOS-1.K)
       NEATHANKE (CURPOS-1-K)
       IF (CUMPOS.EG.1) PREVED
       IF (CUMPOS. JE. NPLT) NEXT#0
       IF (PREV.EU.0) 50 TJ 210
       WALTE(1.2107) J.NAMES(N) . MHEV. J.NAMES(N)
2107 FORMAT(T5."P".12.2.45.T15."C".212.2.45.T25."-1.")
       IF (NEXT. EQ. 0) GO TO 240
210
       ADITE (1.2108) J. NAMES (K) . J. NEXT. NAMES (K)
2106 FORMAT (T5. "P" . [2.2.45. T15. "C" . c12. c . 45 . T25 . "1.")
       BUNITHES
240
       CONTINUE
250
   RIGHT MAND SIDE SECTION
       ## [TE(1.2008)
2008 FORMAT ("DHS")
   MAX FUR EACH FLIGHT TYPE TOTAL
       30 300 Kal . WIF
       -RITE(1-2009) NAMES(K) . MAXELT(K)
 300
 2009 FORMAT (T5."HMS"+T15."T"+45.T25.13)
   MAX FUR EACH PILUT TOTAL
       DO 310 JEL-NELT
        (1.L) xAm. ( (01(5.1)371cm
 310
 2010 FORMATITS. HEMS" . T15. "0" . 12.2 . 725 . 13)
```

```
C MANGES SECTIONS
C USING RANGES TO SET MIN CONSTRAINT ON MILUT TOTALS. MAX
C MAS SET AT RIGHT MANO SIDE.
       (1105-1)3T1w
2011
      FOHMAT ("PANGES")
      DO 400 J=1.NPLT
      (Set) XAM- (Jet) XAMES
       ## (1.2012) J.4
-00
      CONTINUE
2012 FORMAT (T5."RANGES".T15.""".12.2.725.13)
   HOUNDS SECTION SET UPPER AND LUMER INTEGER BOUNDS FOR EACH FILDT/FLIGHT
C TYPE COMBINATION
       (E105-1)371cm
2013 FORMAT ("HOUNUS")
       37 500 J=1.NFLT
       79 500 K=1.NTP
       WALTE (1.201-) IUM-J.NAMES (K) . "44 (J.24K-1)
       15-4-5-11 AAM+ (X) 23MAN-L-011 (4105-1) 3710m
500
      CONTINUE
2014 FORMAT (A4. "BOUNDS" - TIS. "P" - 12.2-45-125-131
       DATA IUP.ILC /4H UI .4H LI /
c
       #PITE(1.2015)
2015 FURMAT ("ENDATA")
       RETURN
       ENJ
       SUBPOUTINE CHANK (PILOT. TOTAL . - ANK . HANK 2 . F 2) . RETURNS (AGAIN)
       IMPLICIT INTEGER (4-Z)
   CHECK FOR RANK PROBLEMS
       DIMENSION WANK (5) . MANKE (50.5) . P2 (50.5)
C
   PANKS IN LEGAL PANGE?
       DU 10 J=1+5
       IF(#ANK(J).LE.0 .04. WANK(J).5[.TU[AL) 55 TO 100
įÛ
   PANK ALREADY ASSIGNED TO ANOTHER MILOT?
       50 20 J=1+5
       KERANK (J)
       IF (HANK2 (K.J) . NE.U) GO TU 200
0ء
       CONTINUE
```

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APPENDIX E

APPENDIX E

FORMATTED INPUT

The computer listing in this appendix is the output of the FORTRAN computer assisted scheduling program generated by the CARDS subroutine. It serves as the input to the CDC APEX III LP software package.

NAME WUWS L TWD	PANNELL		
L TSAT L TMAV			
L TACRT			
L TSAH			•
L INIGHT L ICOLS			
UN TOTALS	TWD	1.	TSAT 1.
DN TOTALS	TMAV	i.	TSAT 1.
UN TOTALS	TSAP	i.	TVIONT 1.
ON TOTALS	TCOLS	1.	L 227
F 505			256
F 503			229
L 204			F 530
L 205			F 535 F 531
F >06			F 533
L 207			234
L 208 L 209			35 م
7 -10			L 236
r HII			L 237 L C1416#D
r -15		*	£ C1416∉D £ C1699#0
C 513			L C0932#0
L P14 L P15			L C3211%0
L = 15			F C1114mD
L 17			F C130540
r 518			L C0235#0 L C3517w0
L -19			L C1720-0
F 550			C202440
F 455			L C2415WD
L P23			L C1525WG
1 -24			L C2529W0
L P25			r cseo⊷an
r -50			2 6200-40

CONTUNE CON L C130 MAY
L C191 MAY
L C191 MAY
L C192 MAY
L C293 MAY
L C293 MAY
L C200 MAY
L C200 MAY
L C200 MAY

1

.

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L C18105AR
L C10335AH
L C133035AH
L C29315AH
L C29315AH
L C31135AH
L C31025AH
L C36255AH
L C36255AH
L C37115AH
L C37115AH
L C1025AH
L C1025AH
L C1025AH
L C1925AH
L C1925AH
L C1925AH
L C2425AH
L C2425AH
L C2425AH
L C2425AH
COLUMNS 20140
                       Two
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                                                                201
      -01541
                       TSAT
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                                                                                 1.
      POIMAY
                                                                201
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      -011CBT
                       TACET
                                                                2)[
                       TSAR
TNIUMT
TCOLS
                                                                101
      -01548
                                                                                 1.
      -UINIGHT
                                       1.
      -05#0
-05#0
                      T#U
C1402-0
CU235-0
TSAT
                                                                2012
                                        -1.
                                       1.
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                                                                                 1.
                       C11025AT
C02245AT
TMAV
      PUZSAT
      202044
                                                                204
                       TACBT
      POZACAT
                                                                200
                                                                                 1.
      163420-
                       C1>02ACbf -1.
                       C02364C6T 1.
                       TSAR
      202548
                                       202
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      205675
                       CLIOZSAP
                      CUZO4SAH
TNIGHT
TCULS
THU
      ~02542
      -DENIGHT
                                                                ₽02
      -USCOL'S
                                                                203
      -03WU
                                       i.
      203541
                       TSAT
                                                                PU3
                                                                                 ı.
                      TMAV
TACBT
TSAR
C330JSAH
      -03MAV
-03ACBT
-035AH
                                                                                 1.
                                                                203
                                                                2,3
                                       -1.
                                                                203
                                                                                 ١.
      203562
      203548
                       CUJZYSAR
      703NIGHT
                      TNIGHT
TCOLS
                                                                203
                                                                203
203
                                       1.
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      -04-00
                       Tab
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                      C250-=0
C0-10=0
T54T
      204#0
      -04-0
                                       ı.
      PULSAT
                                                                                ı.
                                       1.
-1.
                                                                P (14
      204547
                       C2-0454T
      -045-1
                       CO-ZUSAT
                                      1.
      206M4V
                      VAMT
      -0-may
      POSMAY
                       CO-LOMAY
                                       ١.
      -044CST
                       TACHT
                                                                -
                                                                                ١.
                      TACHT i.
C2Y0-ACST -1.
      2044C9T
      POSSCOT
                      C0-15ACST 1.
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PUESAN	ISAN	i.	204	1.
-0-519	C020-54H	-1.		
-0-548	COLZUSAN			
POWNIGHT	INLUMI	i.	٠٠٠-	1.
PO4CULS	TCULS	1.	364	i.
20540	faŭ	i.	5	i.
POSSAT	TSAT	i.	خورونو	i.
20544V	THAV	i.	چرو	i.
POSACHT	TACUT	1.	و، د	i.
POSACAT	CLJUSACHT	-1.		••
P054CbT	CO337ACST			
	TSAR	1.	POS	١.
2055AR			F 4 3	• •
2055AR	C0+0554H	-1.		
POSSAR	COSINSAR	1.	دەد	i.
-05A i Gm T	TNIGHT		205	i.
205CULS	ICOLS	<u>.</u>	-46	i:
206-0	1-0	<u>.</u>	240	i.
-065AT	TSAT Tmav	ļ.	709	i:
-06MAY	TACET	1.	-00 -00	i.
POSACBI		1.	- 00	••
POSACST	1834c0c5	-1.		
POSACHT		i.	ورو	1.
2065AR	TSAR	1.	200	4.
2065AR	CIJUOSAN	-1.		
-05SAR	COOJOSAN	<u>.</u>	.	
POONIGHT	TNEGHT	1.	206 206	1.
-00CULS	TCOLS	<u>.</u>		
207au	TeU	i.	207	1.
207521	TSAT	ļ.	207	1.
POTMAY	TMAY	1.	7 0 4	į.
POTACET	TACBT	1.	207	1.
PO7SAR	TSAR	4.	297	1.
207548	C14075Am	-1.		
PUTSAR	COTIBSAN	1.		
≥07NIGHT	TNĮĠĦŦ	i.	₽07	1.
207CULS	TCULS	4.	201	1.
-08=0	Two	1.	عرا د	1.
-062x	75 4 7	1.	ーッと	1.
POHMAY	TMAV	1.	208	1.
PUBACHT	TACHT	1.	>06	1.
208542	TSAR	1.	205	1.
PUBNIGHT	T* [G#T	1.	Pub	1.
2090000	TCJLŚ	i.	Pud	1.
-09 - 0	T #U	1.	2.)7	1.
>04#O	C1504=0	•i.		
しんみゃり	C0432#0	i.		
-095AT	TSAT	l.	ټو. د	1.
2075AT	C230454T	-i.		
2095AT	COYLESAT	1.		
POSMAV	LMTA	1.	204	:.
~03MEV	CIJOYMAY	-1.		
POGMAY	COYLUMAY	1.		
POWACHT	TACBT	4.	244	1.
-094C=T	COSOVACST	- i •		
-094CdT	CUYZJACBT	1.		
PURSAR	TSAR	i.	-07	1.
PODENT	CZJOYSAH	-i.		
-09548	C040554~	L •		
209NIGHT	THEGHT	l .	₽û→	1.
POSCULS	TCOLS	1.	204	1.
-10-0	TaU	1.	PiU	1.
-10mU	C0-10-0	-1.		
21000	C1012+D	1.		
PIOSAT	TSAT	1.	PIU	1.
PIOSAT	CZSLOSAT	-1.		
PIOSAT	CIULZSAT	1.		
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PIOMAY	TWAY	١.	-iu	1.
710-AV	Cillumay	-1.		
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2105AR	TSAR	1.	-10	1.
-105AH	C12105Am	-i.	• ••	••
PIUNIGAT	INIUMI	١.	ن ۽ ج	1.
-10COLS	TCULS	1.	F10	1.
-11-0	C3211#0	1.	v 11	1.
-11-0	CILLAND	1.		
-1154T	TSAT	1.	Pli	ı.
PILSAT	CISILSAT	-1.		
-115AT -11may	1444 1444	1.		
-11-av	CSSIIMAV	· i ·	-11	1.
-11444	Clilumav	1.		
2114CoT	TACHT	1.	P11	1.
PliaCST	CSATTACBL	-1.		
-11274 -117081	C1:204CdT	-		
Plisar	C371154R	i. -i.	-11	1.
-1154#	C110454#	i.		
HINIGHT	TNIGHT	i.	211	1.
TITCOLS	TCULS	1.	F11	ļ.
-15-0 -15-0	T#U C1∪12#0	i.	915	1.
-15-0				
-125AT	15-1 15-1	i .	PlZ	1.
-12541	CIDIZSAT	_		
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21244	C2412-AV	i. -i.	215	1.
7 1 SaTA	CIZZOMAV	1.		
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2157691	C2J124CeT	-1.	•	
71254R	TEDASESIO	4.	21.	
712544	C2-125AH	1. -1.	Pic	1.
-1254R	CIZIUSAM	1.		
PIZNIGAT	TNIGHT	1.	515	1.
SISCORS	TCOLS	l.	₽15	1.
21340 213547	Tau TSAT	1.	ويد	1.
3 3MAV	TMAV	i.	P13	1.
-13M4v	CBALIMAY	-i.	-13	••
213×4V	TACST	1.		
2134C8T 2134C8T	TACSI	1.	واط	1.
PISACRT	CISTORCS	-1. 1.		
J13544	TSAR	i:	٠ و ن ٠	1.
-1354m	CSILISAR	-1.		
31354F	C1 306546			
-13culs	TNIGHT TCULS	1.	619 514	1.
-10	140	i.	212	1.
216-0	C1-10=0	i.		•••
-16647	T5≜T	1.	3 <u>1 </u>	1.
- I FMEA	TMAV CO÷lemav	l •	×1*	١.
-1-444	Cl-lames	1.		
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216542	TSAR	1.	» į •	i.
21-54-	C051-54-	-1.		
Plusia Plunight	C1-075AH TN[GMT	1.	131 4.	
119H1	1.41001		*14	1.

2100712	TOULS	ì.	>1-	۱.
215-0	TeU	i.	ء ۽ ج	1.
215.0	52-15-0	-1.		
31540	C1525-U	i.		
PISSAT	ISAT	i.	خزن	1.
315547	CSTISSAT	-i.	* -	
PISSAT	C1532547	1.		
	LATA		- (5	1.
P15MAV	CO-15-AV	-1.	-1,	••
PISMAY				
-1544V	C1537M4V	į.	-15	1.
PISACST	TACHT	1.	F15	••
PISACST	CO-154Cal	-1.		
215≙CoT	CISOZACOT	1.	-15	1.
-155-4	TSAR	١.	F13	٠.
215275	C20155Am	-1.		
2155	C151954R	1.	41 -	
PISNIGHT	THIGHT	i •	Pla	1.
-150065	rculs	1.	P15	1.
215-0	TWU	1.	519	1.
D15=0	C1-16-0	-1.		
21000	C1509#0	1.		
-155AT	TSAT		₽15	1.
215MAV	TMAY	1.	2:5	1.
PINACOT	TACOT	1.	وات	l.
-12574	TSAM	i.	2.6	1.
P15547	ClaioSAR	-i.	• -	
215542	Cladisar	1.		
PIONIGHT	INIGHT		210	1.
-: 6CULS	TOULS	1.	Pio	i.
-174U	Tab		7 (4	i.
	2351740	-1.	• •	
ن-17 د در م				•
31750 31750	C1 150 40	1.	١, د	1.
-17SAT	TSAT	1.	P1/	i.
# L 7MAY	TMAV	<u>.</u>	517	i:
PLTACET	TACST	1.		
2175AR	TSAR	ļ.	211	1.
PITNIGHT	TNIGHT	1.	21	į.
217CULS	TCULS	1.	217	1.
-1940	? ol	1.	213	1.
2135AT	TSAT	1.	ويو	1.
-135AT	COFISSAT	-1.		
-195AT	Clalisat	i .		
PIBMAY	IMAY	i.	₽15	1.
213M4A	CILLIMAV	-1.		
~ j 2mAv	C1429MAV	1.		
PERCET	TACST	1.	Pis	l.
PIBACET	Clulo4Cal	-1.		
PLBACHT	CISIBACOT	1.		
PASEIC	TSAR	i.	Pis	1.
PIBSAR	CU71sSA#	-1.		
-19524	ClalaSAm	1.		
PIENIGHT	INIGHT	i.	2:4	1.
-19CULS	TCULS	i:	219	i.
21960	Two	i.	Ply	i.
21940	C1117=0	-1.	* • *	••
51440	C1-02-0	_		
		• •	4	1.
21954T	TSAT	1.	- 17	••
21954T	C2-1-54T	-1.	519	1.
~ i dwa'i	THAY	4.	-17	••
7) Juny	C2519MAV	-1.		
PAMPA	C1925#4V	A •	فاد	1.
PIGACET	TACST	. 4 •	514	
2144687	C37144C81			
PIPACET	CTASPACEL	1.		
919524	TSAR	• •	5. 4	1.
2145AR	C15195AH	-i.		

-14544	CIASARAN	۱.			
Inc. intic	INLGAT	1.		214	1.
313C7F2	TCULS	i.		714	1.
>20-D	Taŭ	1.		ں ہے د	1.
-20a0	C1/20=0	• i •			
-50-D	C2u24-0	1.			
P20541	TSAT	1.		250	1.
2205AT	CU420SAT	-1.			
PEOSAT	CZUZSSAT	ı.			
-2044V	TMAV	1.		B 50	1.
220M4V	CS#SOWAY	-1-			
55044V	CSOU-MAY	1.			
PZOACBT	TACHT	1:		50	ı.
-204CBT	C242U4C5T	-1.			
-205-A	CZULLACST	1.			
2205AH	CO-ZOSAR	1 .		- 20	1.
22054E	C201554#	-1.			
-20NIGHT	INIGHT			260	
-50C7F2	TCULS	i.		550	į.
-21-0	Tau	i.		P21	1. 1.
22194T	TSAT	i.		551	i.
-21 44V	THAY	i.		PZI	i:
7814081	TACST	i.		ا خ در	i.
-2154	TSAR	i.		261	i.
PZINIGHT	TNIGHT	i.		221	i.
PRICULS	reals	1.		يا تے ہ	1.
255-0	140	ī.		222	i.
PEZSAT	TSAT	i:		255	i.
-22-AV	T⇒av	i.		يۆۋىد	i.
162455	TACH!	i.		250	1.
~22S**	1548	1.		₽ 2 Z	1.
224IGAT	TNIGHT	i.		224	i.
72200F2	TCULS	i.		>55	1.
P23#0	Twu	1.		وير	1.
P2354T	TSAT	1.		577	i.
235AT	C2309SAT	1.			
PZZWAV	TMAY	1.	•	≥ ≥3	1.
23-AV	C3557464	-1.			
~23M4V	CZJZGMAV	i •			
-234081	TACBI	1.		653	1.
-537C31	183ACSPC2	-1.			
-53278	C23124C8T	4 •		653	,
P23548	C2304248	1.		FZJ	1.
23410AT	INIGHT	1 -		253	1.
23CULS	TCULS	•		223	i.
75440	1+3	i:		254	i.
-24.0	C202-+U	-1.			• •
-24.5	C2-15-0	1.			
-245AT	TSAT	1.		250	1.
-245AT	C322454T	-1.		-	
2245AT	C241-SAT	1.			
724M24	TMAV.	1.		بح ⊆	1.
JEWER	CSSCHMAY	-1.			
>24m44	C2-2UMAV	i •			
PSAACHT	TACST	1.		260	1.
~244CB1	C25244CaT	-1.			
-244661	CS-SOACE	1.		_	
22454	1542	1.		254	1.
-24578	C525-274	•1.			
-5-274	C2-1254#				
P26410#1	TNIGHT	• •			1.
284CJLS	TCOLS	ļ.		مام در مام در	1.
-25=0 -25=0	Tw0 C1525+0	i .		262	1.
~ 6340	しょうとうせい	-1.			

ب25س س25	C252940			
25541		4 •		_
	ISAT	1.	265	1.
-259AT	C202554T	-1.		
-255AT	CS210241	1.		
-25mmv	TMAY	1.	225	1.
-2544V	C1 +25MAV	-1.		• •
2544V	C2=11=4V	1.		
PESACST	TALBT	i:	-25	
PESACHT	C36254CsT	-i.	-23	1.
₩254C#T	CS>2+4C81	1.		
-25549	TSAR	à e	₽₹Þ	l.
256278	C232354A	-1.		
2566-5	CSっSゃSax	i.		
-25NIGHT	TNIGHT		ودد	1.
-25COLS	TCJLS	1.	يَةِد	i.
225%	ī =U	i.	~ 25	1.
26-0	C245040	-i.		• •
22540	2250440			
-25541	TSAT	i •	3.14	
men sul		٠,	226	1.
	CIZZESAT	-i.		
-25541	C253754T	1.		
CHRA	TMAY	i.	259	i.
~ 65-4V	CIZZOMAV	- i •		
225444	CZSIGMAV	i.		
² 254CBT	TACET	i.	ه ځ د	1.
P25ACeT	014254051	-i.		• •
PESACET	C25054C51			
-2554R		• •		
-245#K	TSAN	4 -	256	1.
	C302754A	-1.		
~25SAR	C253254H	1.		
-coniumi	TNIGHT	i.	P < 6	1.
-24006	TCOLS	i.	240	l.
-27.40	T a ū	1.	₽27	i.
₽275AT	ISAT	1.	₽27	i.
-2744V	T-AV	ì.	P27	••
PZTACHT	TACET			1.
		1.	-27	1.
275aH	TSAR	i.	227	1.
P274 COHT	TNIGHT	1.	⊬ ∈7	1.
2270065	TCULS	1.	75€	1.
25840	Two	1.	92a	1.
25840	C1220=0	+i.	-	- •
259A0	C203740	i.		
-29541	7547	i.	25	1.
TARAT	CZYZHSAT	-1.	- 63	
PERSAT	C2404SAT			
-5647	TMAY	1.		
559W7A		1.	258	1.
	C3725MAV	-i.		
PAMAY	CSCIZMAV	1.		
TSJABSC	TACHT	1.	P<5	1.
PS94C31	211264081	-1.		
~285AR	TSAN	4.	225	1.
P29549	C. +255AH	-1.	- -	
-29575	C242554H	4.		
PZSNIUMI	TNIGHT	i.	₽2 6	
PZECULS	TOULS			1.
-50mn	1.063	1.	وۆم	1.
	Teu	1.	- 34	1.
-29-0	C252440	- i •		
25940	CASSAD	i.		
-295AT	1521		25.4	1.
2295AT	C022454T	-1.		-
-2954T	CZYZBSAT	i.		
-5044V	TMAY	1.	224	1.
PZOMAY	CLEZYMAY	-i.	-5+	• •
-24444	C5435m4A			
-294CBT	14091	1.	194	
-294CB1	C355A*C#1	4 .	259	1.
- 274671	C32674681	-1.		

3544CP1	CS-0-4C01	1.		
-54475	1525	1.	554	i.
-5027-	C375A27H	-l.		
55625	C2-3154#	1.		
229N15#T	TNIGHT	1.	P2+	1.
PROCUES	TCOLS	1.	654	1.
230mn	T #1)_	1.	0 د €	1.
POSAT	TSAT	1.	ں د د	i.
~30m4v	TMAV	1.	0 د د	1.
030≜CBT	TACBT	1.	230	1.
305AH	TSAR	1.	₽30	1.
P30NIGHT	TNIGHT	1.	ں 3 د	1.
-30CULS	TCOLS	i.	ں د =	l.
31 aŭ	T+0_	1.	Psl	l.
-315AT	TS=T	i •	-31	i -
-31~4A	T-4AV	1.	2)1	1.
P314C81	FACBT	1.	731	i.
231548	TSAR	1.	اذد	1.
-315AA	C5431244	-1.		
231278	C3117248	i •		
-314IGHT	TNIGHT	1.	031	1.
-31CULS	TCULS	1.	₽31	1.
≥32±0	TeU	1.	₽32	1.
P32w0	C0435-0	-1.		
032 م	0#11260	i.		
235671	TSAT	1.	275	1.
2325AT	CISSESAT	-1.		
-32SAT	CJ2245AT	1.		
~35mAA	TMAV	1.	535	1.
-324AV	CS435MAV	-1.		
2354V	C3223MAV	1.		
-324CBT	TACDT	i •	P32	1.
-324C6T	C1232ACaT	-i.		
-324C81	C32294CbT	1.		
PASSE	TSAR	1.	P32	1.
325AP	CSOJSSAH	-1.		
232542	C3237SAR	1.		
235410HL	INTONT	1.	D 35	1.
=35COF2	TCOLS	1.	515	1 .
-33-0	Two	1.	د ڌ م	1.
433541	ISAT	1.	- 33	۱.
~33m4V	TMAV	i.	- 33	1.
~334C=1	TACBT	4.	233	1.
~33542	TSAH	i •	ذوم	1.
n3327h	C1533544	-i.		
~3354H	GA260885	. •		
-334104L	TNEGAT	1 •	P 3 3	1.
#33CULS	TCULS	1.	-33	1.
23440	TeU	1.	P 34	1.
234541	TSAT	1.	- 3-	1.
234444	TMAY	i •	P3•	1.
PSEACHT	TACST	1.	P34	1.
234524	TSAR	i.	234	1.
PBONIGHT	TNIGHT	1.	P3•	1.
934CJL3	TCDLS	1.	A 34	1.
235-0	Teu	1 •	235	1.
235uU	C0235=0	-1.		
-35-U	C3517-0	i.	•	
2355AT	TSAT	4 •	- 15	1.
#35M4V	THAY	1.	235	1.
2354C3T	TACAT	1.	335	1.
~355AR	TSAR	1.	ۇر ^چ	1.
#35NIGAT	TNIGHT	1.	235	1.
-35CULS	TCOLS	1.	در د	1.
P36=0	Tau	1.	P 36	1.
23654T	TSAT	1.	-36	1.

	~36~4v	[MAV	1.	ه د ح	1.
	236444	C3-13MAV	1.		- •
	P364CbT	TACET	1.	230	1.
	PSSACHT	TBDACES	-1.		••
	2354C5T	C3oZSACBT	1.		
	P34SAR	TSAR	•		
			1.	P36	1.
	PBASAR	COOJOSAR	-1.		
	-365AR	CJoZoSAR	1.		
	-3641CHI	INIGHT	1.	P 36	1.
	236COLS	TCULS	1.	36 د	1.
	₽37 ₩ U	ľ⊯Ú	1.	١٤٦	i.
	-37 eU	C2337=0	-1.	. •	• •
	P37SAT	TS47	1.	7 و د	
	P3754T	C2637541	-1.	F31	1.
	P3754T	C371554T			
			1.		_
	237MAV	[MAY	1.	237	1.
	23744V	C1537MAV	-i.		
	-374AV	C3725MAV	1.		
	₽374CBT	TACBT	1.	P37	1.
	237ACBT	COSSIACET	-1.	=	
	P37ACBT	C3719ACBT	1.		
	-375AH	ISAR	1.	P 37	1
	-375AH	C3237SAR		-31	1.
			-1.		
	23754A	C3711SAR	1.		
	P37NIGHT	THIGHT	1.	۶۶ <i>۲ د</i>	1.
	₽37CULS	TCULS	1.	P37	1.
~~S					
	⊀ #5	T #O	405		
	RHS	TSAT	วรีโ		
	~MS	THAV	عَادَ ا		
	HHS	TACHT	157		
•	-HS	TSAR	313		
	4HS			•	
	-	TNIGHT	+11		
	ans.	TCULS	255		
	~ ~ 5	201	39		
	~~5	202	97		
	77S	203	49		
	445	294	97		
	245	205	76		
	445	200	89		
	#MS	207	ĕÝ		
	4-S	204	34		
	4mS	204			
			76		
	2-5	210	47		
	745	211	¥7		
	 5	515	97		
	-45	213	51		
	~ ~ 5	>1 •	39		
	4=5	دار	97		
	√HS	-15	áì		
	-45	217	57		
	245	Pla	57 69		
	-4S	717			
		250	97		
	4HS		97		
	745	155	65		
	4 7 5	255	57		
	٦٣Ş	P23	76		
	~mS	250	97		
	4MS	25	97		
	4 ≈5	P25	97		
	√mS	227	39		
	JAS .	P25	97		
	HIS	224	ý.7		
	445	230	62		
	4HS	231			
			99		
	≺™S	- 35 -	97		

HMS	ووه	87	ZUNUĢE IU	2025AR	10
4H\$	- 34	57	ri agnuds	P0254H	5
4mS	₽35	øĠ	ni adnude	POZNIGAT	lj
mm\$	P30	76	ri adunds	205N1CH1	6
HMS	P37	97	SUVUCE IU	202CULS	13
HANGES			LI 30UNUS	POZCOLS	•
RANGES	201	¥	01 30UVDS	ں سافہ 🛭 🗲	12
RANGES	20S	13	LI BOUNDS	0•د0د	9
RANGES	₽03	12	20106 IU	203547	13
HANGES	204	13	CI HOUNDS	POSSAT	10
RANGES	P05	7	UI BOUNDS	203MAV	10
HANGES	200	12	LI BOUNUS	POSHAV	¥
PANGES	907	12	ZUMUOE IU	-03ACeT	6
RANGES	ಎ೦ಕ	9	LI BOUNDS	POJACHT	•
MANGES	P04	7	SUMUL IN	20 3SAH	11
HANGES	- 1 u	13	LI BOUNUS	203548	6
RANGES	P11	13	24406 10	POINTORT	11
HANGÉS	215	13	LI BOUNDS	POJNIGHT	6
~ANG€S	13ء	•	2GMUUE 10	POJCOLS	25
-ANGES	-1-	12	LI SOUNDS	PO3CULS	19
-ANGES	15ء	13	UI HUUNDS	~ () ~ = ()	10
PANGES	216	6	LI JOUNDS	-0440	1-
MANGÉS	P17	12	UI BOUNDS	PO-SAT	15
RANGES	Pis	12	LI HOUNUS	2045AT	15
HANGÉS	-17	13	20MUOr 1U	POLMAY	12
RANGES	-20	13	LI JOUNUS	POLMAV	10
HANGES	P21		UI BOUNDS	POWACHT	12
HANGES	222		LI HOUNDS	PO-ACST	3
HANGES	223	12	SONUOE IU	DO45AH	10
HANGES	224	13	LI BOUNDS	POSSAR	.
RANGES	225	13	SUNDOR ID	PO-NIGHT	15
RANGES	225	13	LI HOUNDS	PU-NIGHT	6
RANGES	27	• 9	SUMUOF IU	POSCOLS	13
HANGES	₽ <u>S</u> B	13	LI BOUNDS	POSCULS	à
HANGES	P29	13	UI BOUNUS	20540	12
PANGES	230	• 2	LI BOUNDS	-05WD	ă
RANGES	P31	12	UI BOUNUS	POSSAT	13
RANGES	جَ رَدِ	i3	LI BUUNUS	PUSSAT	ij
HANGES	23 3	12	SUNUOE 10	POSMAV	10
₹ANGES	٠34	12	LI BOUNDS	POSMAV	8
FANGES	235	16	UI HOUNUS	POSACOT	10
HANGES	236	7	LI JOUNUS	PUSACHT	- 4
HANGES	730	13	SCANOR IN	20554	11
DOUNDS	J ,		LI BOUNUS	2055Ak	7
20MUDE 1U	≥01#U	ò	SUMUUS IU	POSNIGHT	11
LI BOUNUS	P01#D	ž	LI HOUNUS	PUENIGHT	•
SCHUCE IN	POISAT	10	ZUMUOE 1U	POSCULS	12
LI BOUNDS	POISAT	12	LI SOUNUS	POSCULS	10
UI BOUNDS	POIMAY	5	26000E 1U	206∉∪	iż
LI BUUNUS	POIMAV	ž	LI DOUNUS	206#∪	
UI BOUNDS	POLACET	5	SUMUDE IU	PUSSAT	13
LI BOUNDS	POLACET	ž	CUMUDE 1J	POSSAT	iū
SUMUOF IU	POISAM	5	SCHOOP IN	POSMAV	io
LI SUUNDS	POISAR	ž	LI BOUNUS	PONAV	3
SONUOE 1U	THUINICA	6	SCHUOE 10	PUBACET	ă
LI SOUNUS	POINIGHT	2	SUMUOE 1J	PODACUT	š
20NUOE 1U	POICULS	ş	200005	20554	11.
LI BOUNDS	>01COLS	6	LI BOUNUS	20254	• • •
01 900v02	2016052	10	SUMUUE IU	POSNIGHT	1 Í
LI HOUNUS	205An	13	L1 300N03	POBNIGHT	
20,006 10	POZSAT	15	SUMUOE IC	2050005	52
LI BOUNDS	-02SAT	16	LI BOUNUS	PUSCOLS	17
SUNUOF IN	POCMAV	12	SUMUSE 10	207#D	غذ
LI BOUNDS	PUSMAY	12	LI BOUNUS	70140	
SUNUOE IU	POZACHT	12	200003 200006 10	PUTSAT	13
SCANOE 17	POZACST	. 5	SCHUUE 11	2075AT	
		3	C. 300,403	- 9 () = 1	7

UI	30UNUS	-G7MAV	10	SUMUOE 10	P12.00	٠.
ĹΪ	SUMUSE	POTMAY	š			16
		•		LI SOUNUS	21540	ÌΞ
UI	BUUNUS	POTACHT	ş	CGMUUE IU	PIZSAT	16
LI	BOUNDS	POTACHT	7	LI BOUNDS	PIZSAT	16
UI	さいいい	2075AR	11	SUMUDE IU	PIZMAV	
LI	BUNUS	PUTSAR	ă			12
				LI HOUNDS	PISHAV	10
U	SUMUSE	POINIGHT	11	UI BOUNUS	PIZACHT	12
LI	SUMUSE	POTNIGHT	6	LI HOUNUS	2124CBT	
10	BOUNUS	PU7CULS	25			
LΪ	ZONUOS	POTCULS	-	U! aUU NDS	215240	10
			13	ri agunds	515270	4
υſ	9004DS	うひょうり	6	CONDOE ID	PIZNIGHT	15
LI	ZUNUOE	POSWU	2	LI JUUNDS	PIZNIGHT	
υĪ	SUNUS	POSSAT	10			9
				SUMUOR IU	ってていてら	13
LI	SUNDE	POASAT	2	SUNDE 11	=12CULS	ø
υſ	BOUNUS	POOMAV	9	SUMUDE 10	213=0	11
LI	20MUDE	POSMAV	2			
					P13=0	7
UI	SUMDE	P04AC8T	5	267UOE IU	2135AT	12
LI	SUNUS	POSACST	2	FI ROUNDS	PLISAT	7
υI	BOUNDS	POdSAH	õ	SONDOR IL	PIZMAV	
Li	SUMUSE		5			¥
		POOSAR	2	ri aonnds	DISMAY	5
υį	SUNUOF	POSNIGHT	9	2UNUOE IU	PIBACET	7
LI	SUNUS	POMMIGHT	2	LI BUUNUS	PIJACOT	2
UI	SUNUS	PUSCOLS	7			
LÏ	ZUNUS			SUMUUE IU	21354R	y
		≥0°C0LS	6	LI 300%US	-13SAR	7
Uſ	300705	204MD	12	UI BOUNUS	PLINIUMT	10
LI	BOUNDS	しつよれり	7	LI BOUNDS		
υÍ	BOUNUS	PUVSAT	13		Planight	5
-			13	SUMUOE 1U	PIJCJLS	22
LΙ	000NDS	POYSAT	5	LI BOUNUS	P13CULS	17
UΙ	400705	POSHAV	10	JI BOUNUS	P1-WJ	iż.
LI	SUNUSE	VAMEOR				
υĪ	SUNUS	POYACET	10		21-=0	7
				UI BOUNUS	Pl⇔SAT	13
LI	GOUNDS	POYACST	5	LI BOUNDS	P1-SAT	+
UI	300~US	2042AH	11	PUNDS IO	PIEMAY	10
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ĬŪ	SUNUS	POYNIGHT		_	PIWMAY	Ś
_			11	UI BOUNDS	Pl-ACsT	5
LI	40UNDS	207NIGHT	•	LI BOUNDS	71-ACsT	7
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UI	BOUNDS	Pluacat	12	UI BOUNDS	215SAT	
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				LI SOUNDS	HIMMAY	7
υI	SUNDE	PILNIGHT	15	DI BOUNDS	Plaacet	7
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υI	ZUNUS	-170065	19	U1 30	SUNDS	PZZSAH	6
LI	せいいろいい	P17CULS	12		DUNUS	25524	3
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υI	SUNDS	PZBNIGHT	15	SUNDE ID	PERACET	8
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APPENDIX F

APPENDIX F

COMPUTER SOLUTION

The computer print-out in this appendix is the result of running the CDC APEX III package with the input from Appendix E.

The print-out includes both a minimum and maximum solution. Specific guidance on interpreting the print-out is found in Chapter III and Appendix E.

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140	PZINIGHI	Z	** LUALA	2.0000	1.00000	5.00000	10.0000	•
\ <u>*</u>	7210015	Ξ	*****	,,00000	1.00000	7.00000	11.0000	•
<u>-</u>	P-2-111	Ī	- 10mm	10.000	00000.	10.0000	13.00000	
74.7	7775A1	Ξ	AC 1 VE	7.00000	00000.	******	7.00000	•
?.	P.C.MAV	Ξ	21 FOR 14	1.00000	1.0000	3.0000	5.00000	•

talatual t	N 414	11.1		514105	COL ACTIVITY	110) (10)	11/11 1 11 mt 4	HAPPER	HAMITAN	
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2	12.2.5.A.R.	7	:	~ 101	00000.	000001	3.00000	6.0000	•	
1 2	100/1001	-	:	21 4-1-11	00000,	00009-1	7.60000	4.00000	•	
1	× 500//4	3	•	1 041 1	000007	00000	12.00000	14.00000	•	
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1	1881	Ξ		AC 11VI	15.0000	00000	#. u000u	13.0000	•	
7	I'S IMAV	Ξ	:	3.7.E.	000001	00000.	7.00000	10.00000	•	
3	P. 1AC.11	Z		A(1 V	00000	00000.1	5.00600	10.0000	•	
3	12 15AH	3		AC I VI	00000	1.00000	7.00004	11.0000	•	
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3	7 80 CA	Z	:	1	12.0000	000001	10.0000	14.0000	•	
3	F. 180	3		ACTIVE	74.0000	1.00000	14.00000	16.00000	•	
3	1 4 7 7 7 11	3		101	00000071	1.00000	00000-71	16.60600	•	
2	VAMA'	3		¥	00000001	1.00000	4.00000	12.0u000	•	
3	1224 At 161	Z		AC I IVE	200007	1.00000	8.0000	12.00000	•	
9	PZNSAH	Ξ	:	HIGH	10.0000	000001	9.00000	10.0000	•	
74	P2481681	Z		At. 11vt	00000-11	1.00000	6.0000	15.0000	•	
4	224COB S	=	:	A Idelli	1 1,00000	1.00000	8.0000	1 1.00000	•	
2	P.P. SHILL	Z		AC I I VE	000000	1.60000	14.00000	16.0000	•	
7.	P.255A1	Z		AL I I VE	10,0000	1.00000	15.00000	18.0000	•	
	P.P. MAN	-	:	11/1/11	12.60000	1.00000	11.00000	12.00000	•	
-	14.74	3		ACTIVE	000000	1.00000	8.00000	12.04000	•	
	1.25SAR	Z	:	****	00000-01	000001	8.00000	10.0000	•	
-	P25Mont	Ξ	:	24.45	00000*51	1.00000	0.0000	15.00000	•	
ž	7.55CG. 5	Z	:	LO.12 H	0000001	1.00000	4.60000	13.00000	•	
27	Period	Z	:	10-01	14.0000	1.00000	14.00000	16.00000	•	
77	P.ChSA	Z	:	X 140	00000-01	1.00000	16.0000	18.00000	•	
77	P.COMAV	Z	:	¥ 10.0	00000	1.00000	10.0000	12.0000	•	
2	PZBACISI	Z	:	1.041.10	7.00000	1.00000	7.00000	12.00000	•	
22	PZASAH	Z		ACTIVE	3.0000	1.00000	H.00000	10.0000	•	
=	THIS INC.	2	:	2 24.40	17.00000	1.00000	6.00000	100000-51	•	
Ì	1.20,CUL 5	Ξ		At 11 VE	1 1.00000	1,00000	H.00040	13.0000	•	
181	1.27 40	Z	:	LUMLH	00000°	1.00000	2.00000	00000.9	•	
791	1275A1	Z	:	x +140	10.0000	1.00000	2.00000	10.0000	•	
Ė	F2/MAV	===		AL I I VE	000000	1.00000	2.00060	6.0000	•	
184	PZIACHI	Ξ	:	LOATR	00000>	1.0000	2.00000	6.0000	•	
181	P215AN	Ī	:	LUATE	7.00000	1.00000	2.00000	5.0000	•	
Jee	"Z/Mbml	Ξ	:	LOM R	2.00000	1.60000	2.00000	4.00000	•	
2	P2/CUIS	Z	:	LUMEN	6.06000	000001	6.000u	7.00000	•	
57	F-2-1411	===	:	ミナナス	15.00000	1.00000	15.0000	10.0000	•	
2	1.28541	Ξ		ACLIVE	10.0000	1.6000	15.00000	14.0000	•	
761	P-CHMAV	Ξ		AC I N	10.0000	1.0000	10.0000	12.00000	•	
2	F24AC.15	Ξ	:	UNITER	14.00000	1.0000	00000.5	14.64000	•	
**	PZUSAN	Ξ	*	UPPER	10.0000	0.000.	8.0000	10.0000	•	
<u>}</u>	Feated Cont	Ξ		AL 1146	99000 - 21	1.00000	90000.4	15.00000	•	
-7:	PZBCULS	2	:	LOALH	11.00000	1.0000	97000.8	1 3.00000	•	
141	P2-7813	Ξ	:	LUMER	90000.41	00000.1	14.00000	16.0000	•	
1.78	PZVSAI	Ξ		ALIIVE	14.0000	1.00000	14.00000	14.0000	•	
1.79	F 2-1MAV	Z		At. I VI	16.0000	1.00400	0000000	12.0000	•	
00%	P 2-3ACIS	Ξ		AL 1 VE	30000.	00000.1	90009.9	7.00000	•	

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Ni Puste 14	NAME	=		STATUS	COL ACTIVITY	100 1 (00)	11140 Liber 4	Hadd then H	MA'CG INAL	
197	P.C. ISAM	Z		AC 1 V.	00000.1	1.00000	0.0000	10.0000	•	
787	Printent	Ξ	:	21,1,11	15.0000	00000.1	6.0000	15.00000	•	
107	アインじゅう	<u> </u>	:	11 1, 1, H1	11.00000	1.00000	3.00000	11:00000	•	
707	1. 10mm	Ξ	:	14.1.K	15.00000	1.00000	9.0000	15.00000	•	
5	1. 3u SA i	Ξ		At. 11 Vt.	000000	1.00040	1.66000	10.0000	•	
200	1. Justav	Ξ	:	14.1.K1	000000	1.00000	4.00000	6.00000	•	
/02	r Juacul	<u>z</u>	:	27.71	00000.4	1.00000	3.00000	000004	•	
7.53	I' JUSAK	Z	:	IJI'''E H	0000004	1.0000	1.00000	00000.4	•	
70.7	Fred Sal	Ξ	:	14 Pedett 1	1.00000	1.00000	7.00000	3.00000	•	
710	P Julius	Ξ	:	3	14.00000	1.00000	10.00000	16.00000	•	
117	t Diwit	Ξ	:	1 041	000000	1.00000	A. 60066	12.00000	•	
212	P 31541	Ξ	:	r ide	13.00000	1.00000	9.0000	13.00000	•	
211	F 11MAV	Ξ		A 1 1 V	10.0000	1.60000	7.00000	10.60000	•	
Z1-	F MACH	Ξ	:	11 J.	300000	1.00000	6.00000	8.00U00	•	
<12	F 31 SAH	Ξ	:	1.0.4	00000.2	00000.1	8.00000	11.00000	•	
417	Palmical	Ξ	:	H TAME	11.00.00	1.00000	6.0000	11.0000	•	
117	F 11 Cot 5	Z	:	F 10 4 H	00000.6	1.00000	19.0000	25.00000	•	
212	r 12mu	Ξ		At. 11 VE	13.60000	1.00000	12.00000	16.00000	•	
77	PJZSAB	Ξ		AC I VE	17.00000	1.00000	17.00000	18.0000	•	
9//	PACHAV	Ξ		At: 1 1 VE	10.00000	1.00000	4.60000	12.00000	•	
177	PAZACHI	Ξ		7 T 7	1.00000	1.00000	8.6000	12.00000	•	
777	PJESAR	Ξ		At. I VI.	00000.4	1.00000	9.00000	16.0000	•	
122	LIVINA A	Ξ	:	# *	15.00000	1.00000	6.00000	15.00000	•	
1,7	P 12Cut S	Ξ		At 11vt	12.0000	1.00000	8.000c	13.00000	•	
557	r' 3 340	Ξ	:	1041	9.0000	1.60000	7.60000	12.0000	•	
177	P 1 15A 1	Ξ	:	1 04 14	7.00000	1.00000	9.66000	1.3.00000	•	
122	r) IMAV	Ξ	:	* 24.45	10.00000	1.00000	8.000au	10.0000	•	
420	PJJACBI	Ξ	:	# t.t.	30000.	1.00000	00000.4	8.0000	•	
6.77	F.J. ISAM	Ξ		AL 1 1 VE	00000 · H	1.00000	8.0000	11.0000	•	
2 N		Ξ	:	HLAAG	11.60000	3.0000	000000.4	11.0000	•	
112	PERCINS	Ξ		AL I IVE	00000-22	1.0000	14.30000	25.0000	•	
28.5	1. 14 MI)	Ξ		AC 11VE	11.00000	1.0000	10.00000	13.0000	•	
4.31	F MSAI	Ξ	:	LUALK	20000	1.00000	00000.4	7.00000	•	
4.7	F 14HAV	2	:	HIPPE K	00000.	1.0000	3.00000	2.00000	•	
(}:	P PuALII	E A	:	1 C*+ E	00000.4	1.00000	6.40000	6.0000	•	
. Ye	F 1:5AH	Ξ	:	1.U*t H	3.60000	90000-7	3.0000	00000.9	•	
112	L'ENICE	Z		X 180 1	00000.>	1.00000	2.0u0un	000ng.,	•	
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>* <	P PSACIST	Ξ	:	2 200	*.0000	00000-1	4.00000	00000./	•	
₹	P.JSSAH	Ξ	:	LOARM	7.00000	1.00000	7.00000	6.0000	•	
447	r timbert	Ξ		AC. 1 1 VE	1.00:00	900000	2.00000	3.00000	•	
947	P.ESCOLS	Ξ	:	コデアス	1 1.00:00	900007	3,00000	13.00000	•	
446	1. 16141)	Ξ	•	18.7.E.	20000	90009.1	10.0000	12.00000	•	
187	P 355A I	Ξ	:	2 - 1 - 1	13.0000	1.0000	10.04000	13.00000	•	
640	P. JUHAV	<u>z</u>	:	LOWER	20000 · ¢	000000	20000.9	00000.01	•	
647	PJEALNI	Ξ		AL LIVE	.5.6000	00000.	0.0000	10.0000	•	
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<u>-</u>		=======================================	# 14.en	9.21	2.0000.5	00000.1	4.0000	14.40000	•
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210	r Joens	<u>-</u>	M 1919, F. M.	10.00000	0.0000	10.0000	10.0000	•
117	FILE	<u>z</u>	****** **	12.00000	1.u0000	9.40400	17.40000	•
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₹	FJIMAV	Ξ	H 42.61	10.00000	1.00000	4.1000u	10.00.01	1.0000
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222	F.375Ale	Ξ	** IF171. K	10.0000	1.00000	8.0000	10.00000	•
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	t Isati	Ξ	At. I I VE	13.00000	1.00000	10.0000	16.00000	•
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147	IP TYMAN	Z	N Jeeff	1.00.00	1.00000	5.00000	7.00000	1.6000
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3	P.JSSAH	Ξ	H JAKI	000000	1.06000	3.0000	99999.9	•
427	Publish	=	111,1,1 H	7.0000	00000	2.00000	3.00000	20000.1
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645	P. 30, Miles	=	# 1,1-ff #	1<.00000	1.00000	10.0000	12.00000	•
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cot acityiir	99799.11	10.00000	16.00000	18.00000	14.00000	3.0000t	10.00000	15.00000	13.00000
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APPENDIX G

APPENDIX G

SCHEDULER'S HANDBOOK

This appendix is designed to provide a simple step by step guide for using the scheduling system developed during research into optimizing sortic allocation in an $\underline{A-7D}$ squadron. This interactive system is designed for the scheduler to use a computer terminal in the squadron which gives access to a central computer facility and the LP program. The actions required can be categorized into three phases: preparation, input, and analysis. These three phases will be explained in chronological order.

The first phase, preparation, involves collecting and formatting required data so that it will be available in the proper sequence for input into the computer. The initial step is to establish the projected planning sorties of each type for the upcoming training cycle. This information must be broken down according to the maximum numbers by WD, SAT, MAV, SAR, NIGHT, and COLS sorties. In addition, for each pilot assigned or attached for flying, the following data must be collected:

Pilot training category (CT or IQT/MQT)

Pilot category (Primary or Staff)

Pilot's current or projected mission status (MR or MS)

Experience level (Experienced or Inexperienced)

Pilots designated as IPs

GCC level assigned (A, B, or C)
Additional tasking (Night or SAR)

Pilot ranking for each type sortie

Collection of this data can be simplified by generation of a local form with columns arranged similar to the example in Figure 7. With the data available and formatted for the input process, it will take from twenty to thirty minutes to input the information to the computer.

The input phase is not complicated and does not take any great amount of training to accomplish. The first step is to gain access to the computer system. The procedures required to accomplish this task are normally generated locally and will be provided by the local DPI. Once access to the system is obtained, the scheduler must bring the FORTRAN computer assisted scheduling program into the local working space for execution. When the program is executed, a series of questions appear on the display device. The questions and required responses are illustrated in Figure 8.

In addition to the questions which will appear on the display device, the program contains several error statements which will appear when improper data is input. The computer error messages which may be generated and the required responses are illustrated in Figure 9.

After the data for each of the pilots has been entered the scheduler must input 999 for the last pilot number to direct the program to perform a subroutine to generate the proper format for the input of the output from the FORTRAN computer assisted scheduling program to the LP package for generation of a solution. To generate the solution, the output from the FORTRAN computer assisted scheduling program must be input into the LP package used by the system. This is

				l	QM.	SAT		MAV	ACBT	SAR	R.	NIGHT	COLS		TOTAL
PLANN	PLANNING SORTIES	RTIES					-			•					
PILOT	TNG	IQT/MQT	ыгот	NSW	EXPER	Ä		၁၁၅	ADDITIONAL TASKING	TONAL ING			RANKING	9	
NUMBER	САТ	TNG TIME	CAT	STATUS	LVL		IP	LVL	NIGHT	SAR	MD	SAT	MAV	ACBT	SAR
					-										

Figure 7 Sortie Allocation Work Sheet

Question	Response
l. Total number of pilots?	Enter the number of pilots who will be scheduled for flying during the training cycle.
 Maximum number of WD, SAT, MAV, ACBT, SAR, Night, COLS sorties? 	Enter in order the maximum number of each type sortie forecast to be available for the training cycle.
3. Pilot number?	Each pilot is numbered consecutively from 1 to the maximum entered for the question in number 1. Enter 999 when all the pilots have been entered.
4. Training categoryCT=1, IQT/MQT=2?	If a pilot is entered or already in CT enter l. If a pilot is going through IQT/MQT enter 2.
5. Months to complete IQT/MQT1,2,3,4?	Enter the number of months the pilot is expected to take to complete training in months from 1 to 4.
6. Pilot categoryPrimary=1, Staff=2?	Enter a l if the pilot is a primary unit pilot and a 2 if the pilot is a staff pilot.
7. Status after IQT/MQTMR=1, MS=2?	If the pilot will enter CT and become MR after completion of training enter 1. If the pilot will not become MR then enter 2.
8. Pilot statusMR=1, MS=2?	Enter a 1 for an MR pilot and 2 for a non AR pilot.
9. Experience=1, Inexperience=2?	If a pilot is classified as experienced enter a l otherwise enter a 2.

Figure 8

Question/Response

Ones	Question	Response
.00	10. Is pilot an IPYes=1, No=2?	If pilot serves as an IP or SEFE enter a 1, if not enter a 2.
Ë.]]. GCC levelA=1, B=2, C=3?	Enter the appropriate number for the assigned GCC level: A=1, B=2, C=3.
12.	12. Ranking for WD, SAT, MAV, ACBT, SAR sorties?	Enter in order the ranking for each type sortie for each pilot.

Figure 8 (Continued)

Sta	Statement	Response
- :	l. Illegal entry try again	Check and reenter required data. This will normally occur when an entry is not one of the inputs allowed. For example, inputting a 3 when only a lor 2 entry is allowed.
	Max pilots allowed is 50 must change program	This will be printed if the number entered for the total number of pilots in question 1, Figure 9, exceeds 50. If more than 50 pilots are assigned the program will have to be modified to make the arrays and matrices larger to accommodate the additional data.
ب	Ranks must be in Range l to # pilots = " "	This entry is printed when a number is entered greater than the total number of pilots entered in response to question 12, Figure 9.
4.	Conflict with pilot " " ranks = " "	This entry is printed when two pilots with the same ranking are entered in response to question 12,

Figure 9

accomplished by following the locally established procedures to run the program. Once the program is run, the output can be routed to a printer or displayed on the local display device depending on local capabilities. Generation of the computer solution completes the input phase and provides the product which is evaluated in the final phase.

The computer solution generated by this process allows the scheduler to evaluate sortic requirements on three different levels. The first level is made up of the gross total figures for each sortic type relative to the input for the planning factors for the training period. The next higher level includes a breakout of total sortics by pilot, but does not break the total sortics down by type. The last level consists of a breakout of sortics by type for each pilot.

Evaluation of the first level involves interpretation of the first eight rows of the CONSTRAINTS section of the computer solution as reproduced in Figure 10. The entries in the RHS UPPER column represents the planning factors input by the scheduler. The entries in the ROW ACTIVITY column are the solutions for the number of sorties required or desired. The entry in the SLACK column shows the difference between the input and the computer solution (ROW ACTIVITY entry). Positive entries in the SLACK column indicate an excess capacity, while negative entries indicate a shortage. The other column of interest is the MARGINAL column. An entry in the MARGINAL column indicates the rate at which the total sorties changes per unit change of the type of sortie. A negative sign indicates an improvement in the total sorties and a positive sign indicates a degradation in the total sorties. By comparing the maximum and minimum solutions the scheduler can arrive

	MARGINAL			MARGINAL	
	RHS UPPER	457.00000 549.00000 359.00000 285.00000 395.00000 534.00000		RHS UPPER	457.0000 549.0000 359.0000 304.0000 285.0000 395.0000 534.0000
	RHS LOWER	INF INF INF INF INF		RHS LOWER	INN F IN
	SLACK	11.00000 32.00000 4.00000 9.00000 64.00000 16.00000		SLACK	53.00000 114.00000 62.00000 55.00000 167.00000 91.00000
	ROW ACTIVITY	446.0000 517.0000 355.0000 295.0000 285.0000 331.0000 518.0000		ROW ACTIVITY	404.00000 435.00000 297.00000 249.00000 228.00000 443.00000 2341.00000
	STATUS	SLACK SLACK SLACK SLACK BINDING SLACK SLACK SLACK		STATUS	SLACK SLACK SLACK SLACK SLACK SLACK SLACK
	TYPE	3555555		TYPE	<u> </u>
	NAME	TWD TSAT TMAV TACBT TSAR TNIGHT TCOLS		NAME	TWD TSAT TMAV TACBT TSAR TNIGHT TCOLS
MAXIMIZE	NUMBER	- 0 E 4 E 6 P 8	MINIMIZE	NUMBER	-08460V8

Figure 10 Level One

at an idea of the range of sorties which could be used efficiently under either limited or plentiful sortie availability.

Using Figure 10 an example can be given to clarify the process of interpretation for this level. The same inputs were used in both the maximum and minimum solutions depicted. From line eight it can be seen that the sorties needed to meet the needs of all the pilots would be 2,341 at a minimum level or 2,747 at the maximum level. When 285 sorties are input as the SAR (line 5) planning factor, the ACTIVITY column shows a solution of 285 sorties with no excess apparent in the SLACK column. The -1 entry in the MARGINAL column for SAR sorties indicates that if an additional SAR sortie could be generated the total number of sorties would improve by one. Evaluating the WD row (line 1) shows there is excess WD sorties available at both maximum (53 excess) and minimum (11 excess) sortie rates. The difference between the two rates, 42 (53-11) sorties, should not be converted to another type of sortie or returned to another unit to satisfy their needs since these sorties can be efficiently used by the unit. Only eleven of the WD sorties should be considered for conversion to another type of sortie or returned for use by another unit. Since the configuration of both SAT (line 2) and MAV (line 3) aircraft are compatible with the SAR mission and there are excess sorties of both types, the excess sorties of either type could be converted to SAR missions and the total number of sorties flown could be efficiently increased by one for each sortie converted to a SAR mission. This same process is applicable for any type sortie where aircraft configurations are compatible.

Level one provided a general view of the total sortic requirements by type. Level two provides a more refined view by allowing the

total allocation for each pilot to be evaluated. To simplify the explanation of the information available in level two, pilot PO4 will be used as an example.

From the minimize section of Figure 11 the minimum number of sorties which should be allocated to PO4 (line 12) would be seventy three (RHS LOWER). The maximum number should be eighty six (RHS UPPER). The difference between the maximum and minimum sorties is thirteen (SLACK) which could be used should PO4 have problems which required extra training. The -1 (MARGINAL) value indicates the total number of sorties for the unit could be improved by one sortie if PO4 were to be given one less sortie. However, since PO4 is already at a minimum level, he should not be given any fewer sorties unless he is to be regressed to a lower GCC level.

From the maximum section of Figure 11 the maximum number of sorties which PO4 should be allocated is again seventy three (ROW ACTIVITY). Since both the maximum and minimum solutions are the same, the scheduler should make every attempt to allocate seventy three sorties to PO4. The -4 (MARGINAL) entry means every additional sortie allocated to PO4 would result in a change of four in the total sorties for the unit. This is true because if PO4 were given one additional sortie the program would also have to allocate additional sorties to other pilots.

When the maximum and minimum solutions (ROW ACTIVITY) for a pilot differ as is the case for PlO (line 18, Figure 11) significant information can be deduced. The difference between the lower and upper rate of flying should be regarded as the minimum number of sorties held in reserve for the pilot. For PlO, four sorties would be

	PPER MARGINAL	000 000 000 000 000 000 000 000		PPER MARGINAL -1.00000 -1.00000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 000 -1.00000 -1.00000 000 000 -1.00000 000 000 -1.00000 000 000 000 000 000 000 000 000
	RHS UPPER	39.00000 86.00000 81.00000 68.00000 81.00000 39.00000 86.00000		86.00000 81.00000 81.00000 81.00000 81.00000 81.00000 81.00000 81.00000 86.00000
	RHS LOWER	30.00000 73.00000 69.00000 56.00000 69.00000 69.00000 30.000000 73.00000		30.00000 73.00000 73.00000 69.00000 56.00000 69.00000 30.00000 73.00000
	SLACK	3.00000 3.00000 13.00000 1.00000 2.00000 4.00000		SLACK 9.00000 13.00000 12.00000 12.00000 12.00000 12.00000 13.00000 13.00000
	ROW ACTIVITY	36.00000 83.00000 73.00000 67.00000 79.00000 39.00000 64.00000		ROW ACTIVITY 30.00000 73.00000 69.00000 56.00000 69.00000 30.00000 73.00000 73.00000
	STATUS	SLACK SLACK SLACK SLACK SLACK SLACK SLACK SLACK SLACK SLACK		STATUS BINDING
	TYPE			17PE 81E 81E 81E 81E 81E 81E 81E
Įų.	NAME	P01 P02 P04 P05 P07 P09 P09	ш	MAME P01 P02 P04 P08 P09 P10
MAXIMIZE	NUMBER	10 112 115 116 118	MINIMIZE	NUMBER 9 10 11 12 113 114 115 118

Level Two

held in reserve and the remaining nine (SLACK) of the maximum solution could be used for another purpose or not used at all.

Level three provides the greatest amount of detail for the scheduler. It allows an evaluation of the various sortic types for each pilot. Pilot POI will be used to explain the evaluation process for this level using Figure 12.

Both the minimum and maximum solutions for pilot PO1 WD, ABCT, SAR, NIGHT, and COLS are equal as indicated in the print-out (lines 1, 4, 5, 6, and 7). This indicates PO1 should be allocated the same number of these sorties under most conditions. The solution further shows that PO1 should be scheduled for between five and ten SAT sorties even though the acceptable range would be from two (BND LOWER) to ten (BND UPPER). The MAV sortie spread is from two to six which is the same as the acceptable limits (BND LOWER to BND UPPER).

An important factor is identified by the -1 (MARGINAL) entry (line 5). The number of SAR sorties available are a limiting factor which was previously noted in level one. If more SAR sorties were made available, the number of SAR sorties allocated to PO1 would increase under the maximum allocation condition. Likewise, the total number of sorties would increase by one sortie for each sortie allocated to PO1.

A negative entry in the MARGINAL column is an indication of who should be given more (maximum condition) or fewer (minimum condition) sorties. The larger the number the greater the effect on the total sorties for each sortie either given or taken away. A positive entry in the MARGINAL column is an indication of who should not be given more (maximum condition) or fewer (minimum condition) sorties.

MAXIMUM								
NUMBER	NAME	TYPE	STATUS	COL ACTIVITY	OBJ COEF	BND LOWER	BND UPPER	MARGINAL
	POJWD	INT	ACTIVE	2.00000	00000	2.00000	6.00000	
۶ ۲	1013A1	** INI	UFFEK	00000	00000-1	000000	60,0000	•
ე ⊄+	POJACBT	**LNI	UPPER	00000.9	00000	2.00000	00000	
ည	POISAR	IN	LOWER	2.00000	1.00000	2.00000	5.00000	-1.00000
9	POINIGHT	INT**	UPPER	4.00000	1.00000	2.00000	4.00000	•
7	POICOLS	** LNI	UPPER	9.0000	1.00000	00000.9	9.00000	•
∞ α	POZMD	INI	ACTIVE	13.00000	1.00000	13.00000	16.00000	
<u>ہ</u> 5	POZSAI	BFY**	UPPER	12.00000	.00000	14.00000	12,00000	
? ;=	P02ACBT	INT**	UPPER	10.0000	00000	8.0000	10.0000	• (
15	P02SAR	INI	LOWER	10.0000	1.00000	10.0000	12.00000	-1,00000
MINIMUM								
NUMBER	NAME	TYPE	STATUS	COL ACTIVITY	OBJ COEF	BND LOWER	BND UPPER	MARGINAL
-	POTWD	INT*	LOWER	2.00000	1.00000	2.00000	00000.9	
7	POISAT	INT	ACTIVE	5.00000	1.00000	2.00000	10.0000	•
က	POTMAV	**LNI	LOWER	2.00000	1.00000	2.00000	00000.9	•
4	P01ACBT	INT**	UPPER	00000.9	1.00000	2.00000	00000.9	•
ှ	P01SAR	**LNI	LOWER	2.00000	1.00000	2.00000	2.00000	•
91	POINIGHT	**LNI	UPPER	4.00000	1.00000	2.00000	4.00000	
_	POICOLS	*LNI	UPPER	000006	00000	000000	9.00000	•
∞ (POZWD	** LNI	LOWER	13.00000	1.00000	13.00000	16.00000	٠
ی 5	PUZSAI	INI DEV**	ACLIVE	13.0000	.00000	00000 51	18.0000	•
2 ==	POZACBT	INT	LOWER	8.0000	1.0000	8.0000	10.0000	• •
12	P02SAR	INT**	LOWER	10.0000	1.00000	10.0000	12.00000	•
				Figure 12	21			

Figure 12 Level Three

The guidelines provided in this handbook apply to the computer generated print-outs from the Control Data Corporation APEX III program and the Burroughs' TEMPO program. Both of these programs are for solving linear or integer programming models.

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